

94 GHz Doppler Wind Radar Satellite Mission Concept and Planned Demonstration Campaigns

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Upcoming European atmospheric missions









Scientific motivations



- What will be the storm track?How fast will it grow?
- How will the wind structure look like?
 - How much precipitation will fall and where?

Courtesy of S. Tanelli, NASA-JPL



- Are the presently used parametrization schemes for convections/turbulence in NWP models adequate?
- Are all mechanisms involved in convective systems well-understood?
- How shall convective phenomena be best-represented in the NWP models?

Objectives



- Observation of detailed 3D motion of the atmosphere under (highly) convective/turbulent conditions and extreme weather events from space
- 2. All weather capability, especially under cloud cover
- Complementary to the ADM/Aeolus (lidar) mission: clear sky, single 35° off-nadir cut of the atmosphere, 200 km sampling
- 4. Understand/quantify the 'wind-cloudprecipitation' connection

MetOp/ASCAT ocean surface vector wind observation, superimposed onto MeteoSat imagery (Courtesy of KNMI)

3rd ISMAR Workshop, Paris, I



esa Conically scanning pencil-beam concept Trade-offs on: - orbit height - ~500 km altitude - 37.8° off-nadir (800 km swath) - off-nadir angle E.g.: - 2.9 m × 1.8 m - antenna size - 8.6 RPM (50 km per revolution) - scan speed D-Doppler info 1.xD-Doppler info 750 2D-Doppler info 700 60 120 180 240 360 420 480 Marack (km) European Space Agency

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Stereo radar concept





 Radar with forward and backwards views within an inclined plane

- Ideally 90° between the two views
- Fine wind vector sampling within the inclined plane
- Requires forward and backward antenna apertures
- Single cut in the atmosphere

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Frequency-diversity pulse-pair (FDPP) technique (1)





$$\begin{cases} \text{quist velocity:} \quad v_{Nyq} = \frac{1}{4T_{hv}} \quad \begin{cases} T_{hv} = 20\,\mu s \Rightarrow v_{Nyq} = 100\,m/s\,@K_a & 37.5m/s\,@W \end{cases}$$

Basic assumption: Radar echoes between V and H channels are well-correlated

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Frequency-diversity pulse-pair (FDPP) technique (2)



Trade-off on pulse-pair interval T_{hv}:

- Small T_{hv} requires high SNR;
- Large T_{hv} reduces Nyquist velocity



Vertical resolution (conical scan)



Assuming: - Cross-scan beam width=0.077°; Along-scan beam width=0.124° - 500 km orbit altitude; 500 m range resolution



Ghost echoes due to depolarization and system cross-talk



There are two sources of ghost echoes:

- 1) due to depolarizations by ice clouds and solid precipitation;
- 2) due to system internal polarization cross-talks.



Multiple scattering and non-uniform beam filling (NUBF)





- Part of signals due to multiple scattering may be **decorrelated** between the H- and V-channels:
 - No ghost Doppler, but increased noise level!
- **NUBF** gives rise to significantly erroneous Doppler estimation

A. Battaglia, M.O. Ajewole, and C. Simmer, "Evaluation of radar multiple scattering effects from a GPM perspective. Part I: model description and validation," J. Appl. Meteorol., 45(12), 206, pp. 1634–1647.

Blind layer





Kobayashi, S., Kumagai, H., and Kuroiwa, H. (2002). A Proposal of Pulse-Pair Doppler Operation on a Spaceborne Cloud-Profiling Radar in the W Band. J. Atmos. Ocean Technol., 19, 1294–1306. doi: http://dx.doi.org/ 10.1175/1520-0426(2002)019<1294:APOPPD>2.0.CO;2.

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Demonstration campaigns (1)





25 m antenna of the S-band weather radar at Chilbolton, UK *3rd ISMAR Workshop, Pari*

- Ground-based demonstration of the FDPP technique for Doppler retrieval with varying pulse interval
- Study effects of depolarization/particle shape and channel cross-talk
- 94 GHz Galileo radar already upgraded to support the FDPP mode of operation
- S-band radar to support calibration of the 94 GHz radar



94 GHz Galileo radar and 35 GHz cloud radar

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Demonstration campaigns (2)





More details/updates: http://www.nawx.nrc.gc.ca

Demonstration campaigns (3)



Objectives of the airborne campaign (Ottawa/Great Lake region):

- Quantifying the spatial and temporal decorrelations between echo-signals in the two polarization channels;
- Correlating in-situ particle size distribution with radar backscatter;
- Quantifying the polarimetric backscatter properties of sea and land surfaces, and their effects on blind zone;
- Acquire high spatial resolution data for modelling non-uniform beam-filling (NUBF) effects in satellite configuration.
- Remark: No multiple scattering is expected in airborne or ground-based configuration.

Cloud particle probes (courtesy of NRC Canada)



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Conclusion



- Synergy and joint campaign opportunities sought with ADM-Aeolus, EarthCARE and ICI mission preparations.
- Chilbolton (ground-based) observation campaign planned to start in Nov. 2015 for a period of 6 months.



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Contact points for campaigns



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