

Retrieval of water vapour atmospheric profiles from microwave observations

Filipe Aires, Frédéric Bernardo

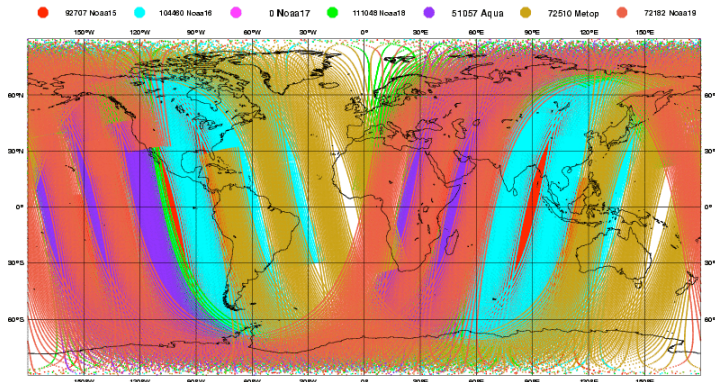
Estellus

and Catherine Prigent

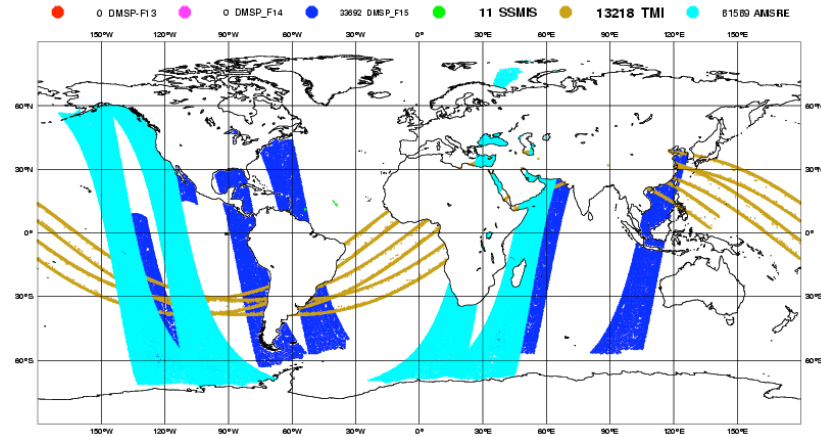
Lerma, Observatoire de Paris

Example of 6-hourly satellite data coverage

LEO Sounders

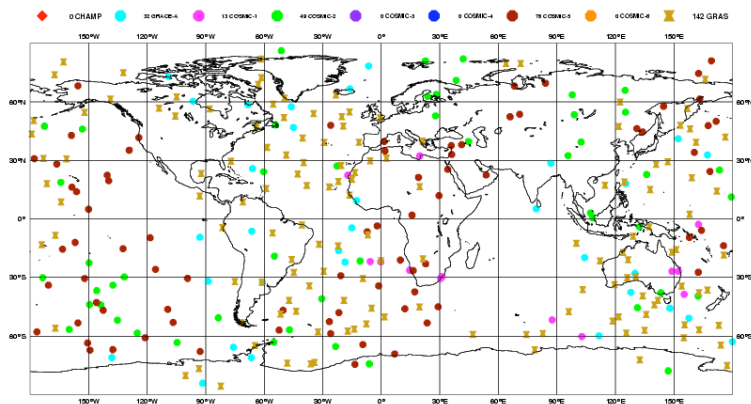


LEO Imagers

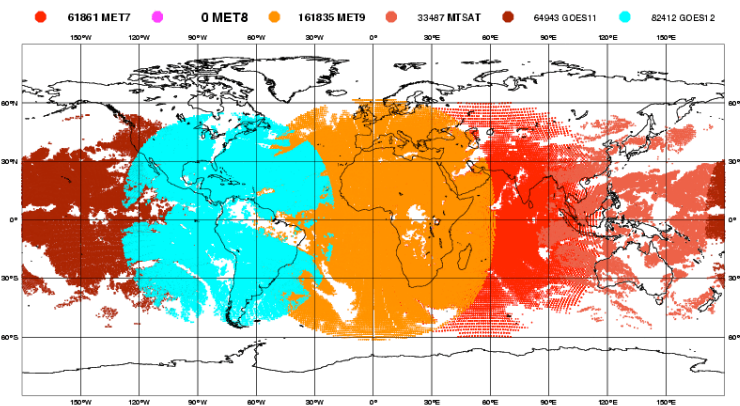


- AMSU-B/MHS on NOAA-17/19, Metop
- SSM/I on DMSP F-15, AMSR-E on Aqua

GPS Radio Occultation



GEO imagers

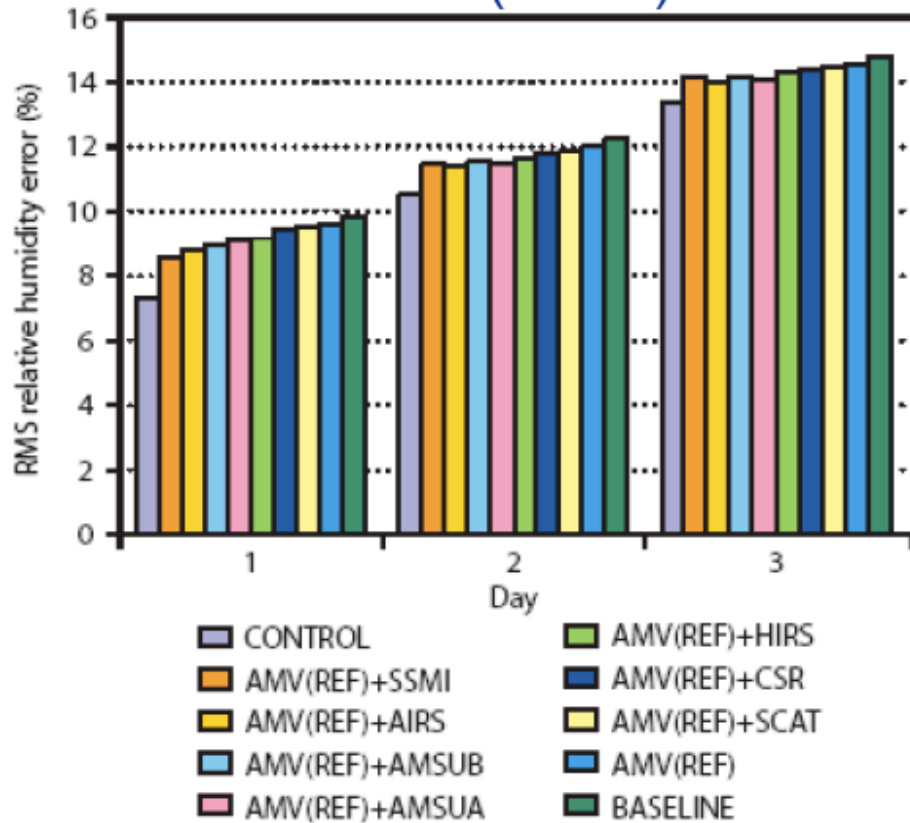


9 April 2010 00 UTC

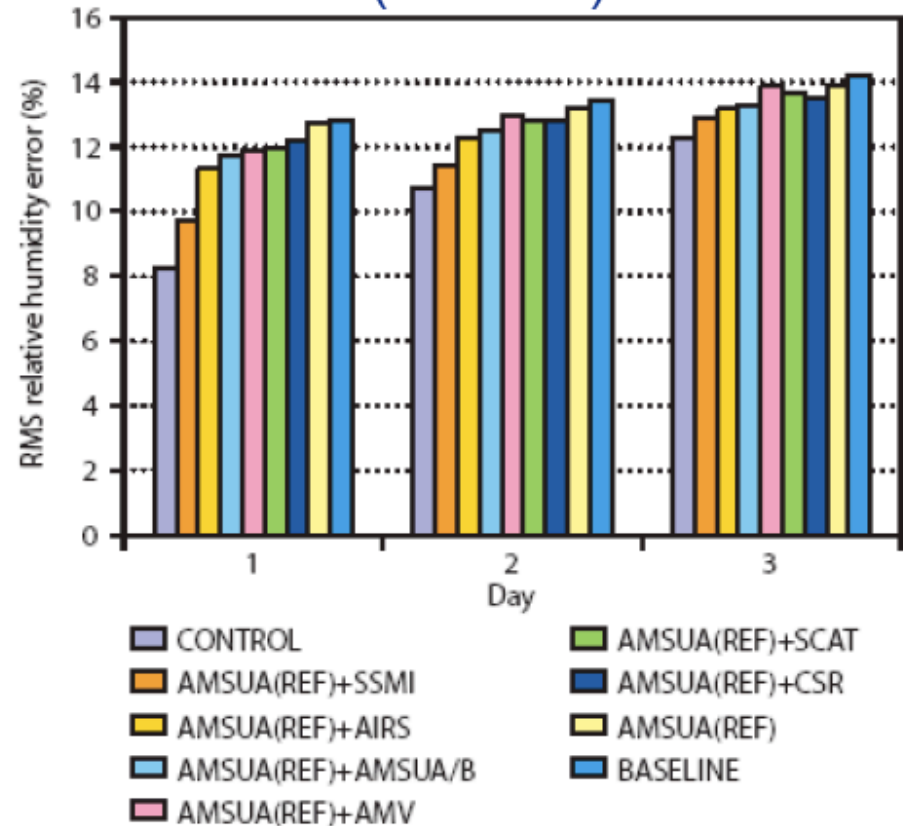
Individual impact of satellite data

850 hPa *relative humidity* RMS error

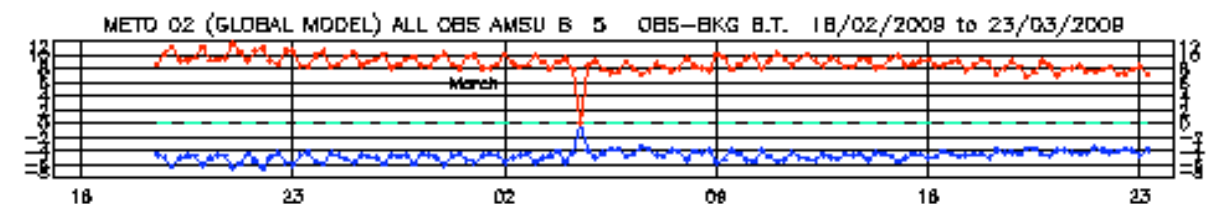
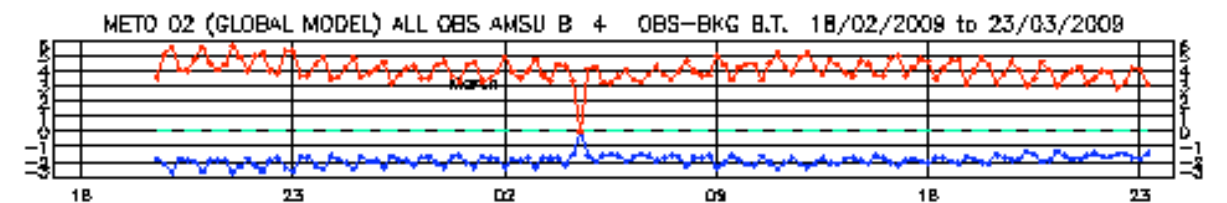
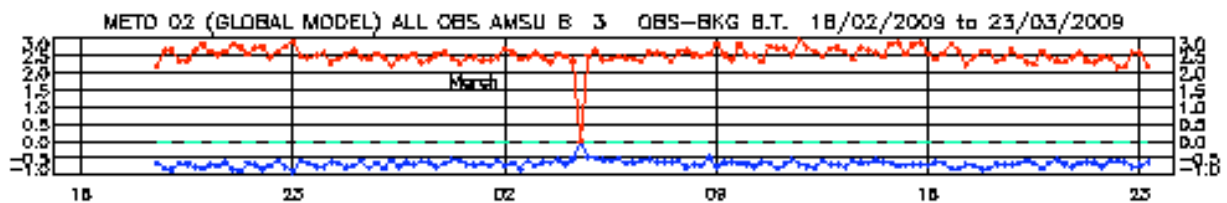
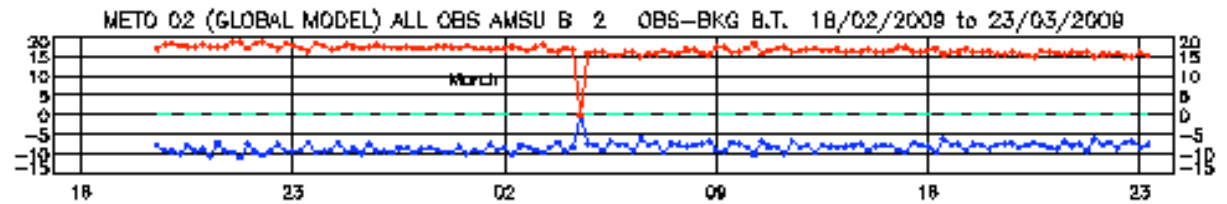
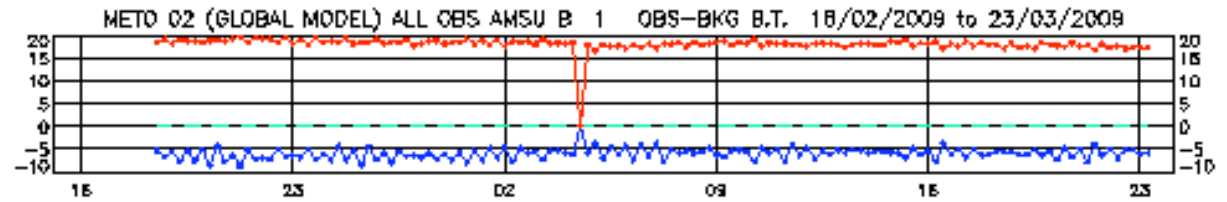
NOSAT + AMVs (winter)



NOSAT + 1 AMSU-A (summer)



Monitoring of the Observed-Background at ECMWF



Much improvements can be done in water vapour channels in the operational centers

Mean
STD

Introduction

- Bonne couverture spatiale en globale (mauvaise résolution temporelle)
- Information intéressante sur la WV

Mais :

- Des problèmes de calibration/validation
- Restitution au dessus des continents difficile à cause de la contribution de la surface (beaucoup de données rejetées à cause de cela, notamment pour la basse troposphère).

Outline

- Total Column Water Vapour avec SSMI
 - First-guess
 - Emissivités de surface
- Sondage de la WV avec AMSU
- Sondage avec AMSU-B/HSB/MHS/Saphir (AQUA/METOP/Megha-Tropiques)
 - Telsem : outil pour First-Guess des émissivités MW
 - Calibration pour l'inversion
 - Outils de validation

Retrieval Results

Table 3. RMSE Error Results for First Guess and Retrievals

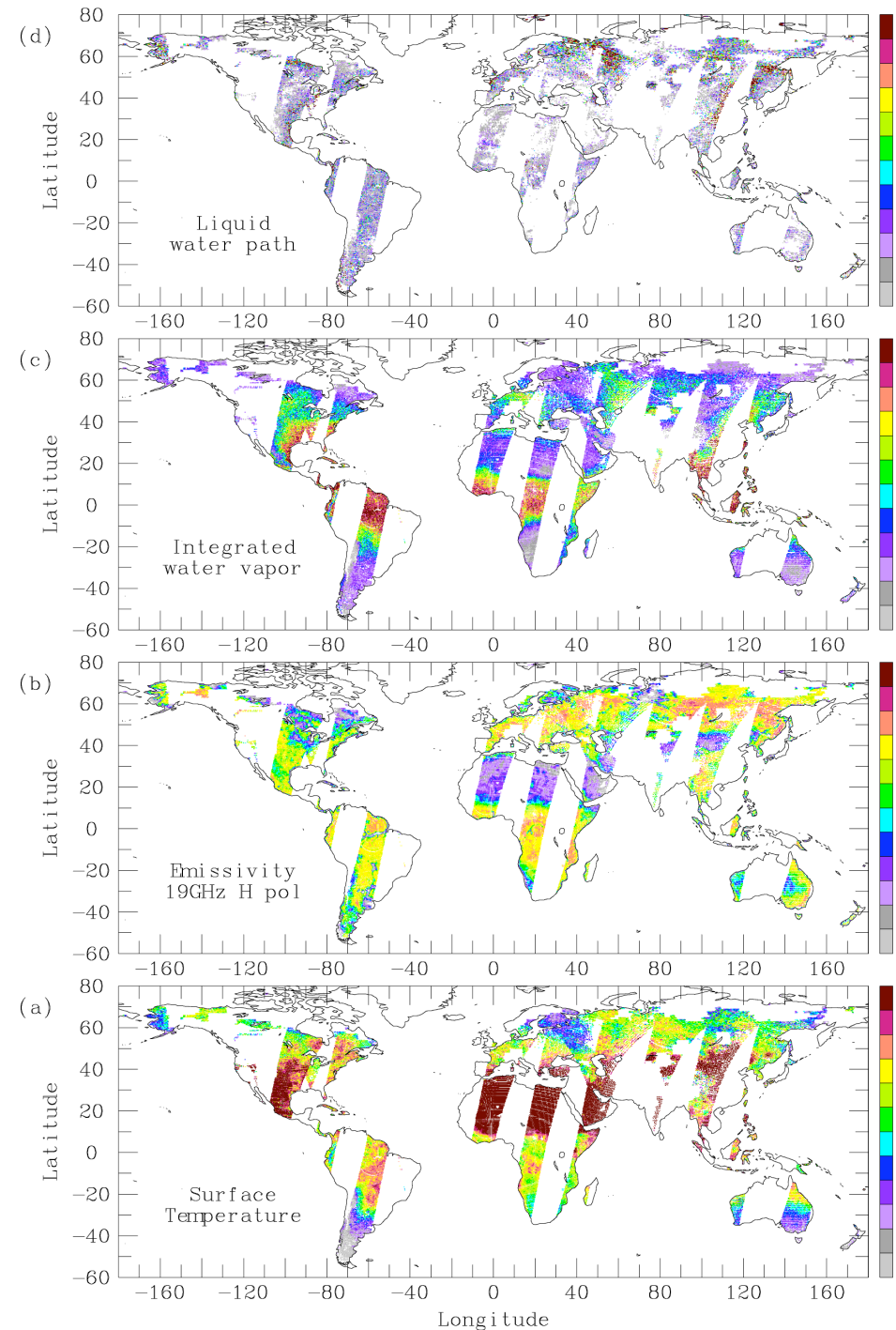
	Observation	NN1		NN2	
	or First Guess Errors	Clear Without First Guess	Clear With First Guess	Cloudy Without First Guess	Cloudy With First Guess
TbSSM I 19 GHz V (K)	0.600
TbSSM I 19 GHz H (K)	0.600
TbSSM I 22 GHz V (K)	0.600
TbSSM I 37 GHz V (K)	0.600
TbSSM I 37 GHz H (K)	0.600
TbSSM I 85 GHz V (K)	0.600
TbSSM I 85 GHz H (K)	0.600
Ta ^a (K)	3.000
Tc ^b (K)	2.000
Ts ^b (K)	4.000	3.470	1.340	3.310	1.570
LW P ^b (kg.m-2)	0.090	0.080
WV ^a (kg.m-2)	40.00 ^c	5.330	3.830	6.860	4.900
Em 19 GHz z V	0.016	0.012	0.004	0.012	0.006
Em 19 GHz z H	0.018	0.011	0.004	0.012	0.006
Em 22 GHz z V	0.018	0.013	0.005	0.013	0.006
Em 37 GHz z V	0.015	0.012	0.004	0.012	0.006
Em 37 GHz z H	0.018	0.011	0.005	0.013	0.006
Em 85 GHz z V	0.020	0.015	0.006	0.016	0.009
Em 85 GHz z H	0.023	0.016	0.008	0.018	0.010

^aNC EP .

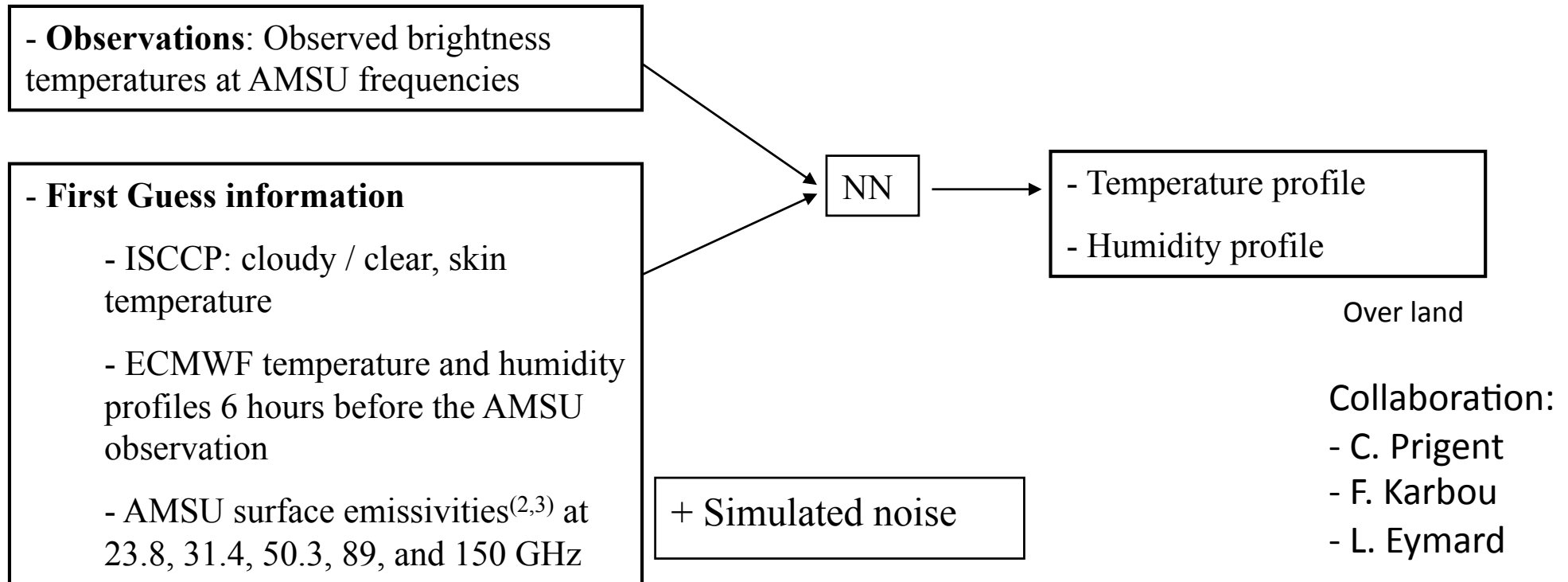
^bJSCCP .

^cIn %.

Aires, Prigent and Rossow, JGR, 2001.
 Prigent, Aires and Rossow, JAM, 2003.
 Prigent, Aires and Rossow, JGR, 2003.



Atmospheric Humidity and Temperature Profiles Over Land From AMSU-A and AMSU-B Observations⁽¹⁾

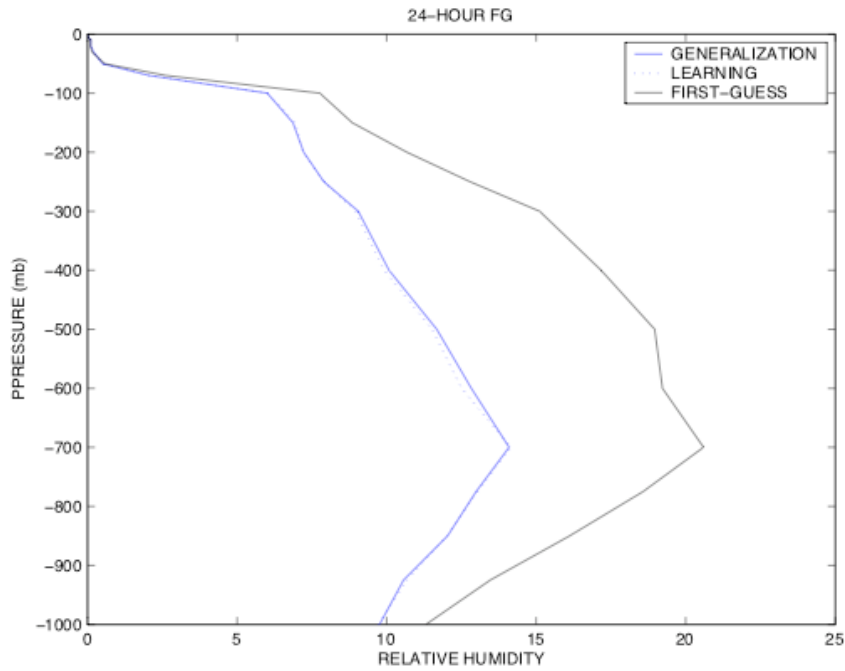


⁽¹⁾ Karbou, F., Aires, F., Prigent, C. Retrieval of temperature and water vapor atmospheric profiles over Africa using AMSU microwave observations. *Journal of Geophysical Research*, 110(D7), 2005.

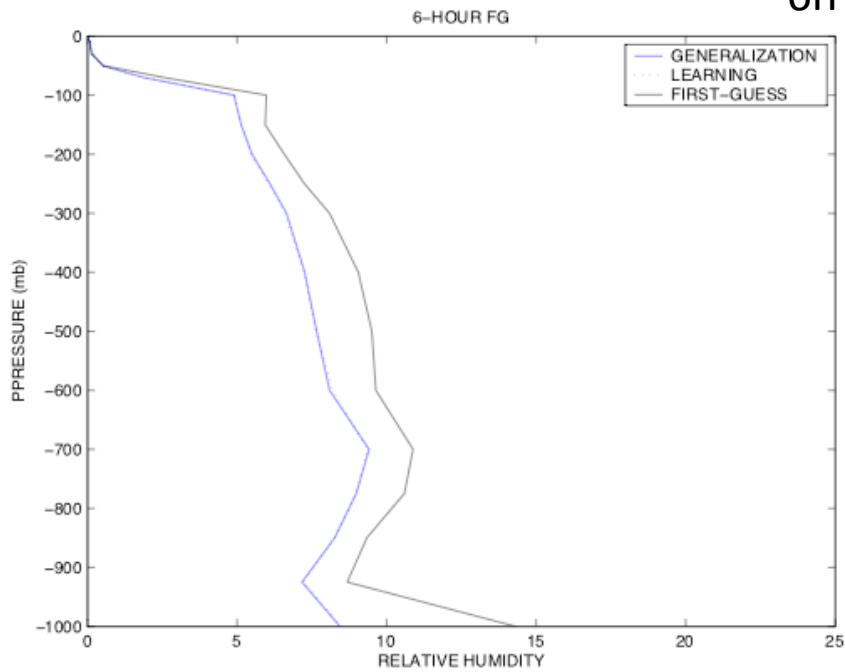
⁽²⁾ Prigent, Rossow, Matthews, Global maps of microwave land surface emissivities: Potential for land surface characterization, *Radio Science*, 33, 1998.

⁽³⁾ Karbou, Prigent, Eymard, and Pardo, Microwave land emissivity calculations using AMSU-A and AMSU-B measurements, *IEEE TGRS*, 43(5), 2005.

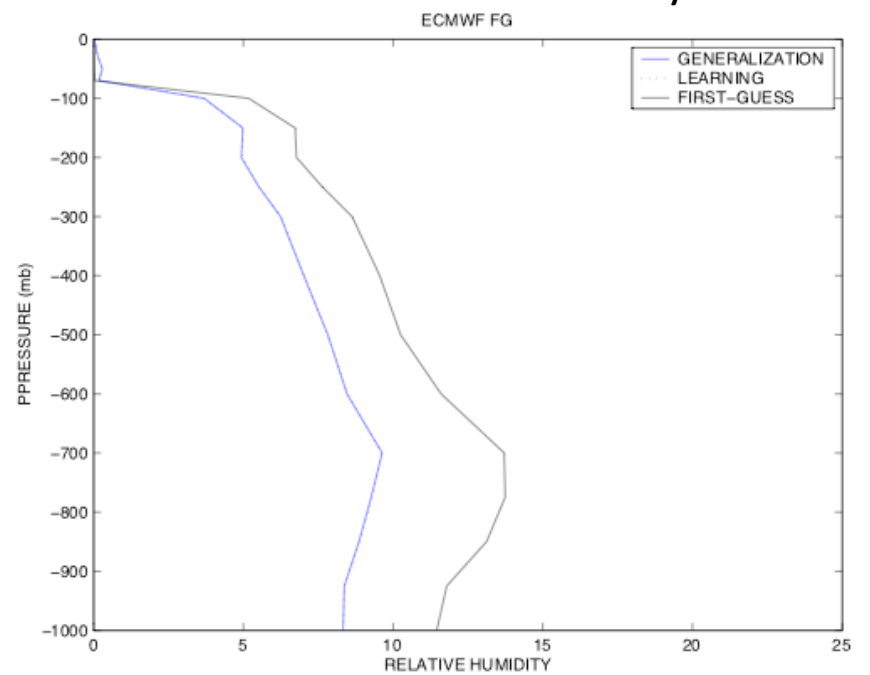
Impact FG for Specific Humidity Profile



24h Forecast



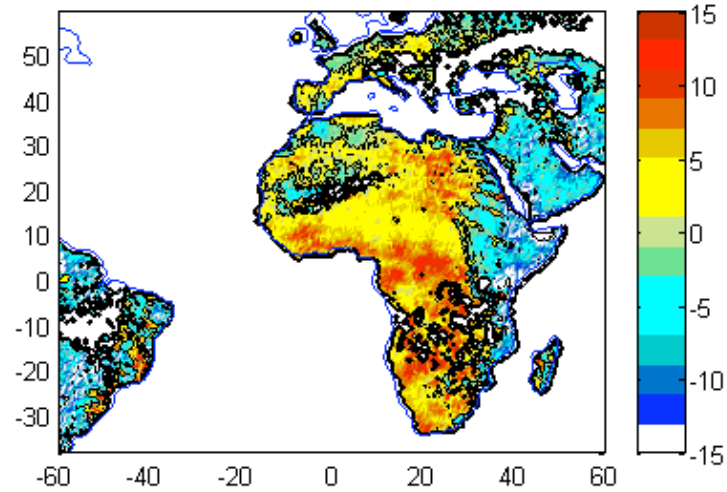
6h Forecast



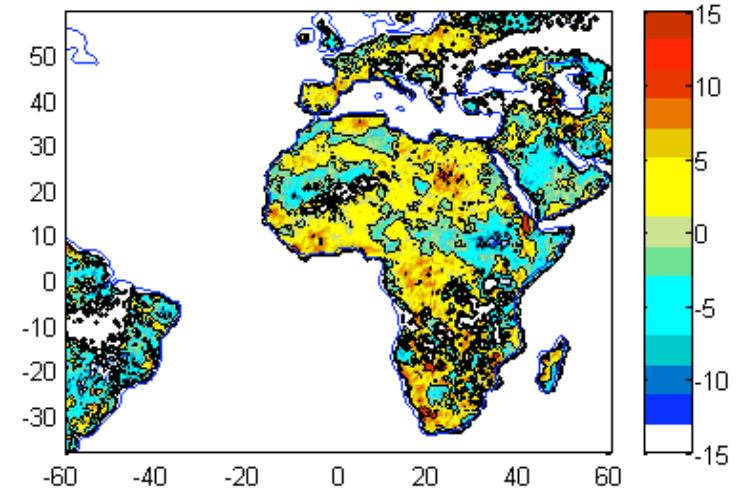
Analyse

Bias Statistics / FG and NN Retrieval

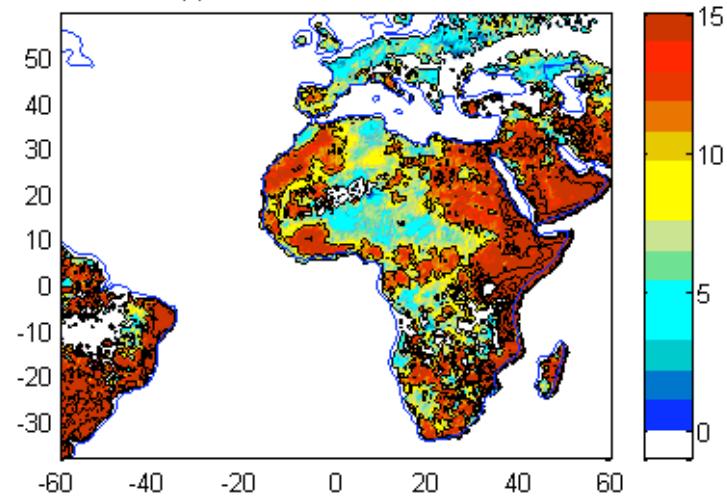
(a) BIAS WV, FG, 1000mb



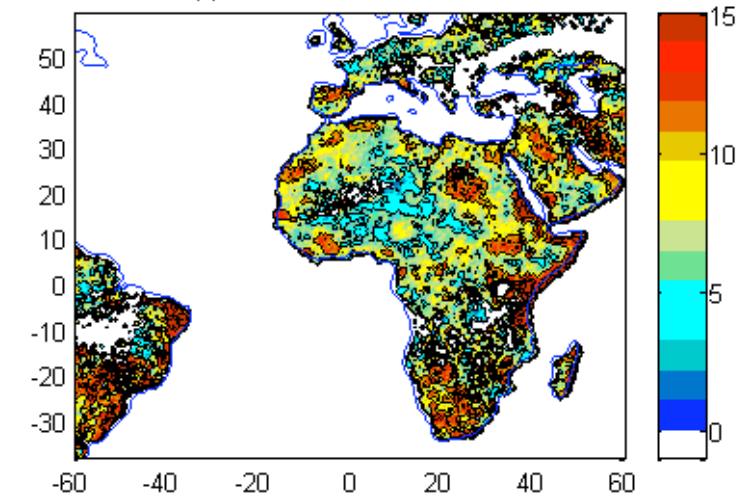
(b) BIAS WV, NN, 1000mb



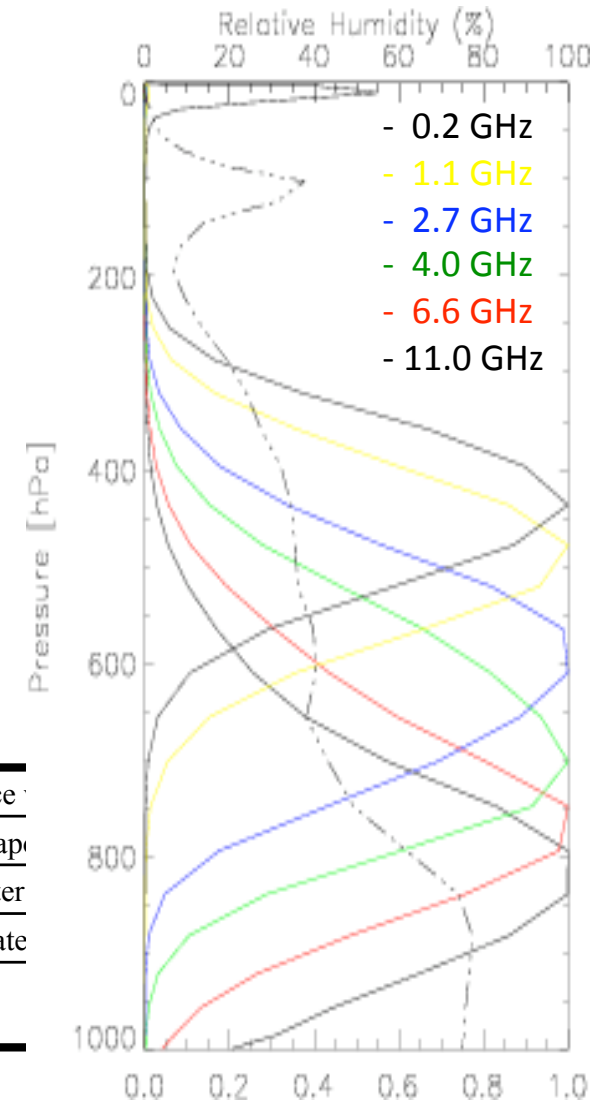
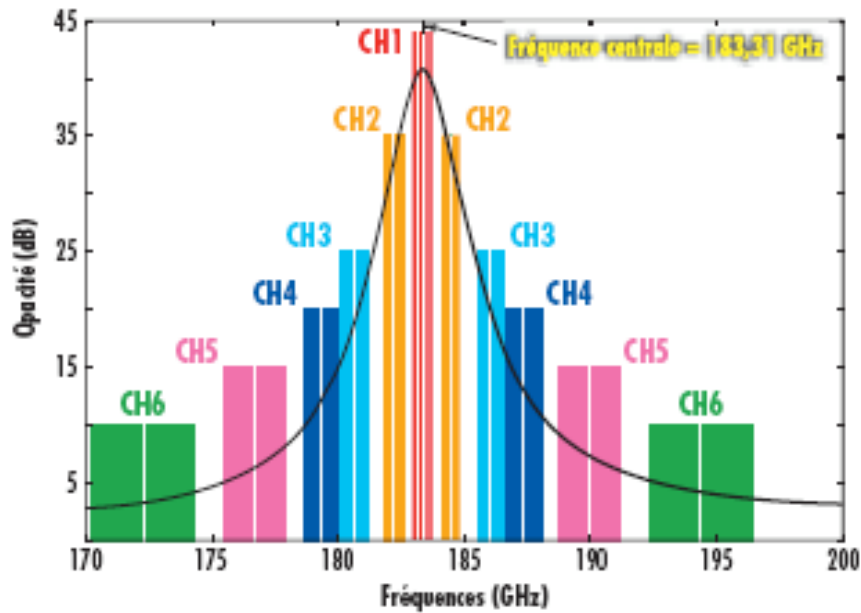
(a) RMS WV, FG, 1000mb



(b) RMS WV, NN, 1000mb



Sondeur Atmosphérique du Profil d'Humidité Intertropicale par Radiométrie

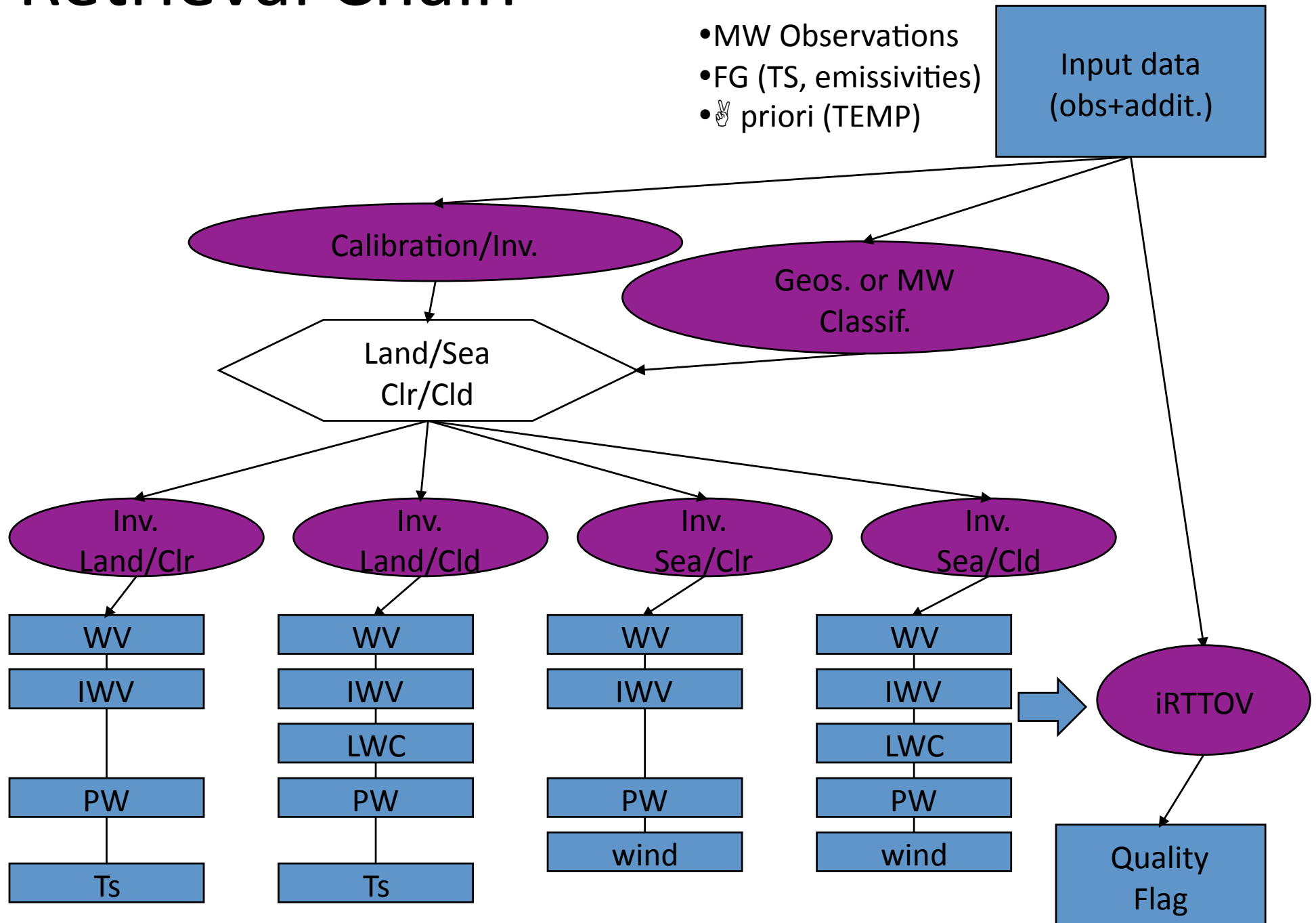


Frequencies	Polarization	Pixel size	Noise	Main use
18.7 GHz \pm 100MHz	V + H	40 km	0.46 / 0.53	Ocean rain and surface
23.8 GHz \pm 200MHz	V	40 km	0.48	Integrated water vapour
36.5 GHz \pm 500MHz	V + H	40 km	0.44 / 0.49	Cloud liquid water
89 GHz \pm 1350MHz	V + H	10 km	0.63 / 0.58	Convective rain rate
157 GHz \pm 1350MHz	V + H	6 km	1.75 / 1.65	Cloud top ice
183.31 \pm 0.2 GHz	H	10 km (at nadir)	2.03	vertical distribution of water vapour
183.31 \pm 1.1 GHz			1.53	
183.31 \pm 2.7 GHz			1.37	
183.31 \pm 4.0 GHz			1.25	
183.31 \pm 6.6 GHz			1/06	
183.31 \pm 11 GHz			0.99	

Saphir
Madras

Retrieval Chain

- MW Observations
- FG (TS, emissivities)
- ✌ priori (TEMP)



A tool to Estimate Land Surface Emissivities at Microwave (TELSEM) frequencies

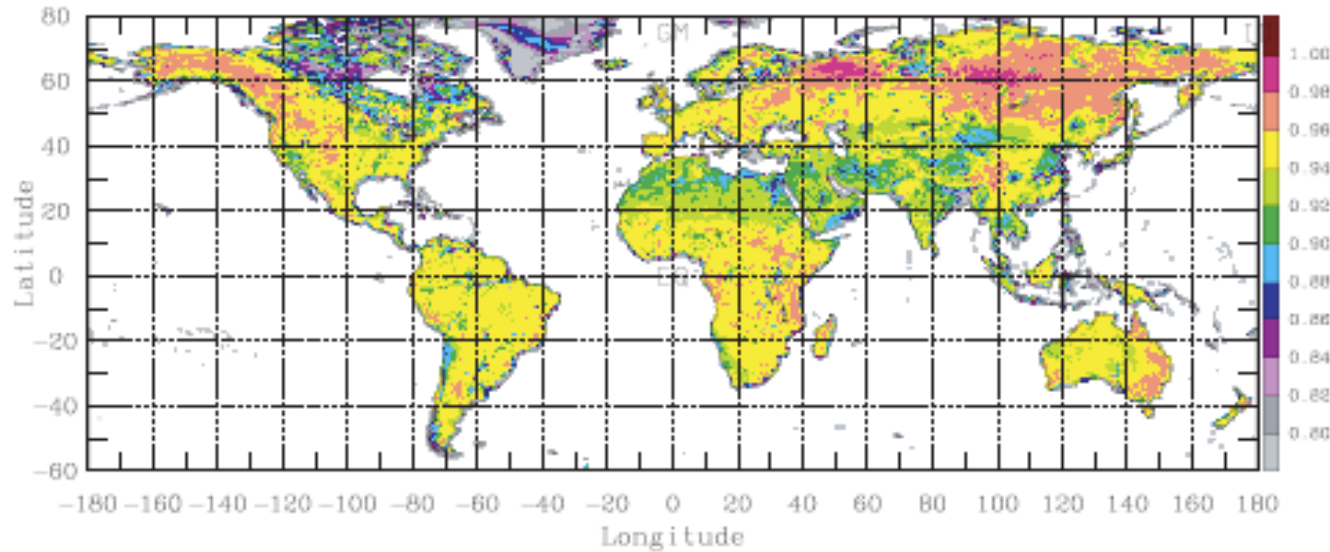


Figure 1. Example of emissivity calculation with TELSEM for September at 31.4 GHz, for 15° incidence angle and vertical polarization.

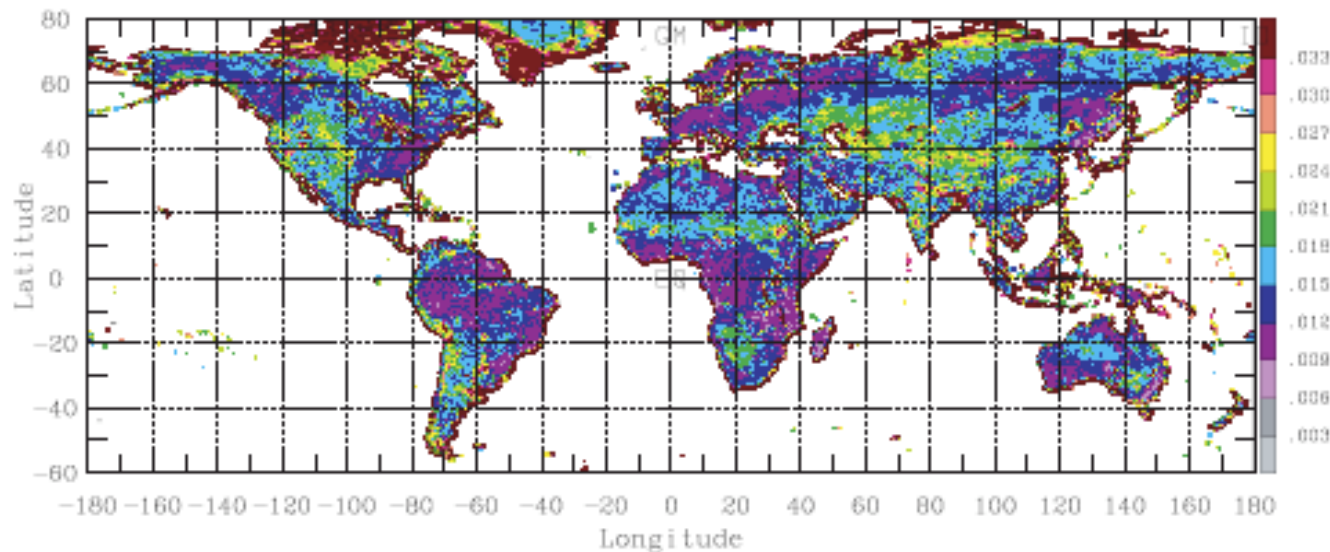


Figure 2. The emissivity uncertainty estimates for September, interpolated at 31.4 GHz, for the vertical polarization at 15° incidence angle.

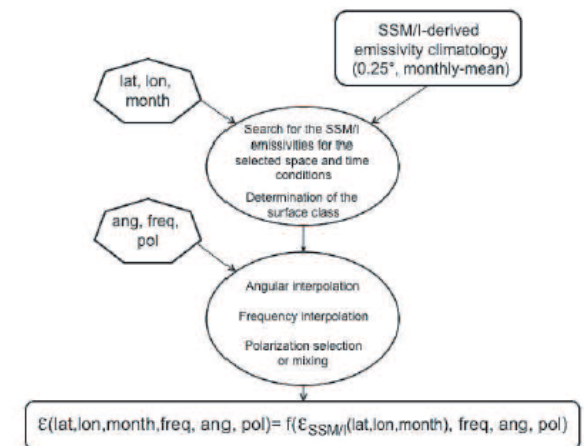
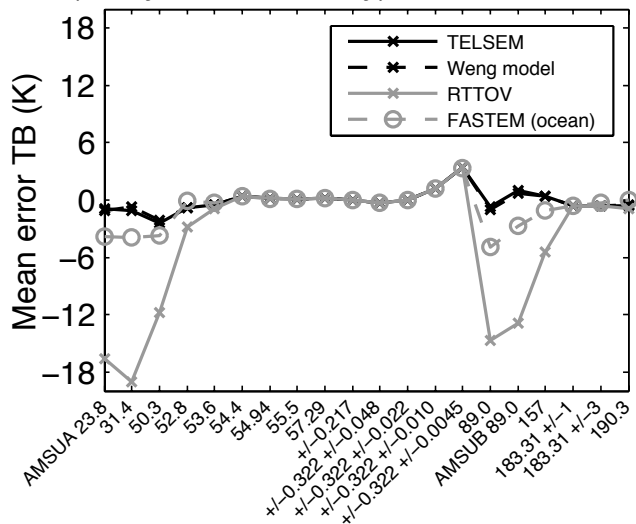


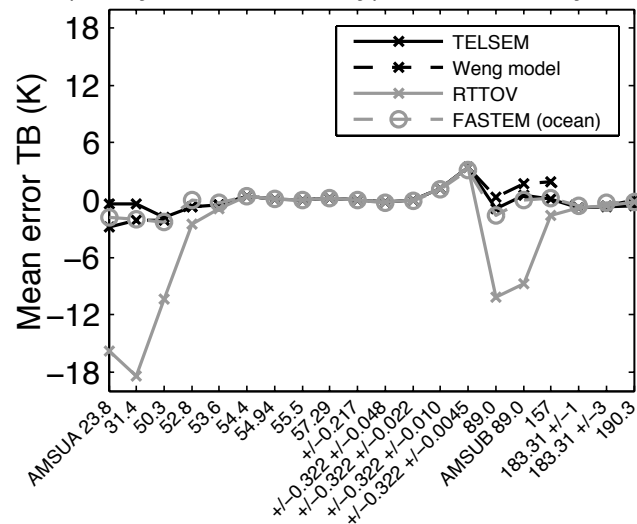
Figure 3. The different steps in TELSEM.

- Prigent et al. 2008, IEEE TGRM
- Aires et al. 2010 (submitted QJRM)

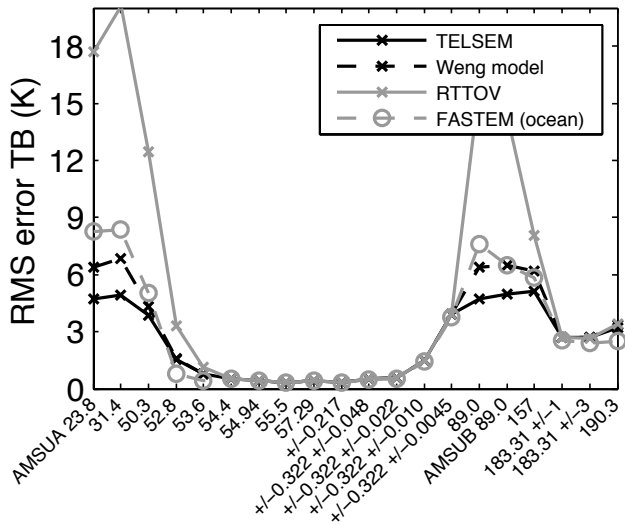
RT(Analysis + Emissivity) – Obs, clear situation



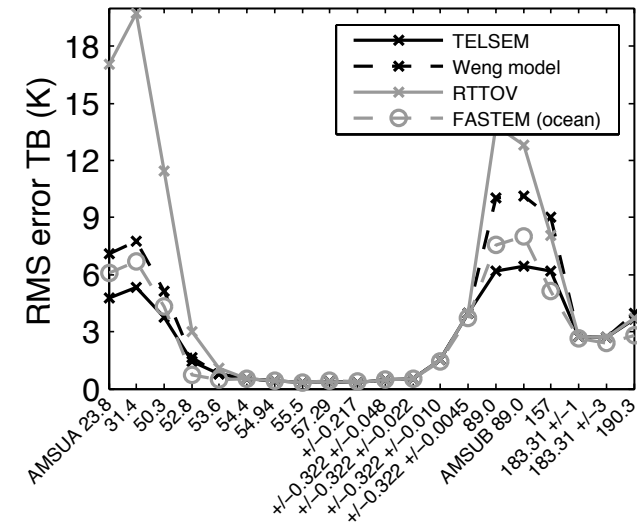
RT(Analysis + Emissivity) – Obs, cloudy situation



RT(Analysis + Emissivity) – Obs, clear situation



RT(Analysis + Emissivity) – Obs, cloudy situation



Calibration for retrieval: General idea

Any retrieval algorithm uses a Radiative Transfer Model (RTM):

- iterative inversion, 1D-var, assimilation: online utilisation
- statistical techniques (NN, Bayes.) : used for the construction of the learning database

→ If this RTM isn't correctly calibrated/corrected to get close to real observations, then the retrieval algorithm will suffer from some problems.

→ **We have developed a dedicated statistical calibration procedure that projects real observations onto the “RTM simulations” space**

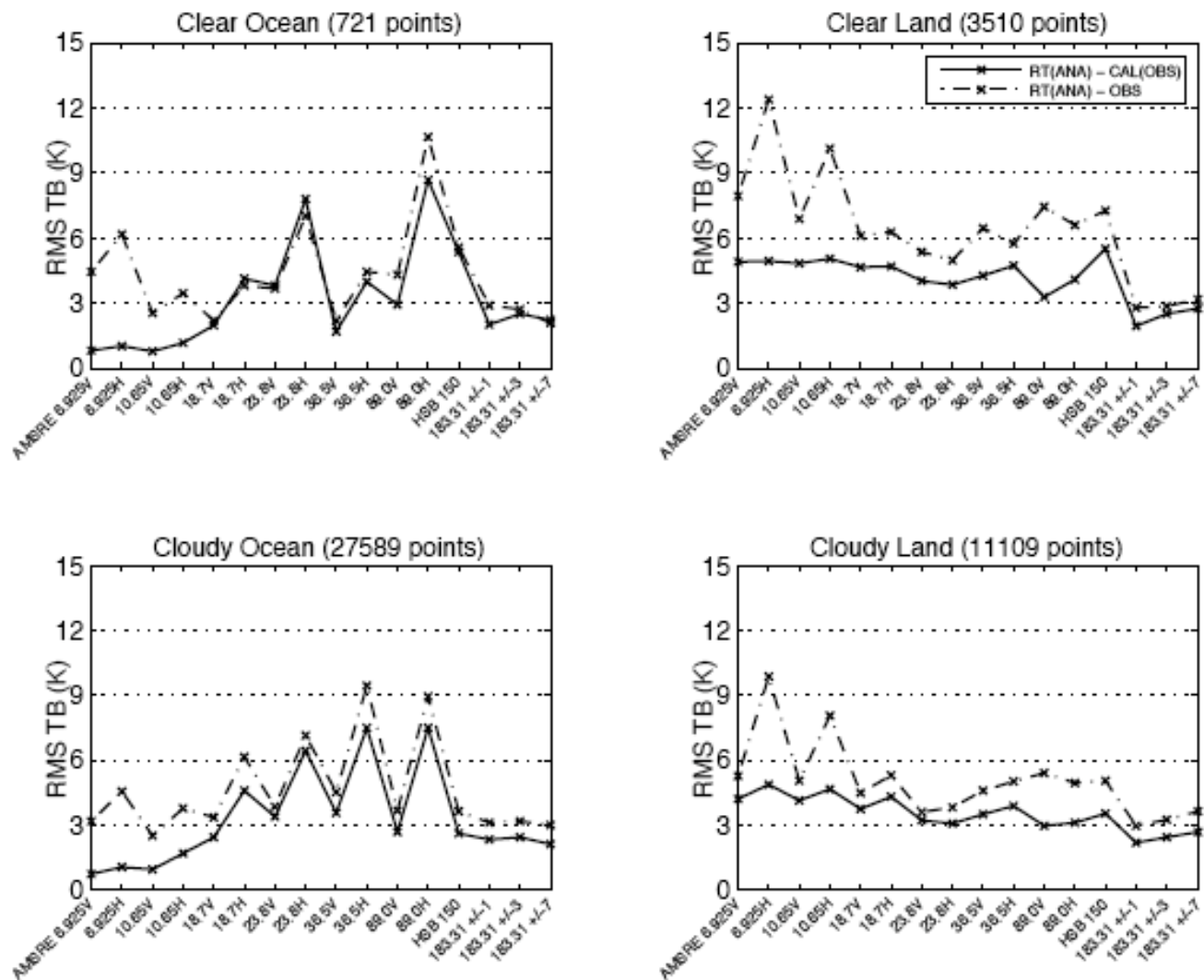


FIG. 2. Root Mean Square (RMS) differences between observed and calibrated data for AMSUR-E and HSB channels. Four cases are considered: cloud free (top) and cloudy without precipitation (down) situations; and for ocean (left) and land (right) scenes. The solid and dashed lines correspond to the RMS difference when using calibrated and non-calibrated brightness temperatures, respectively.

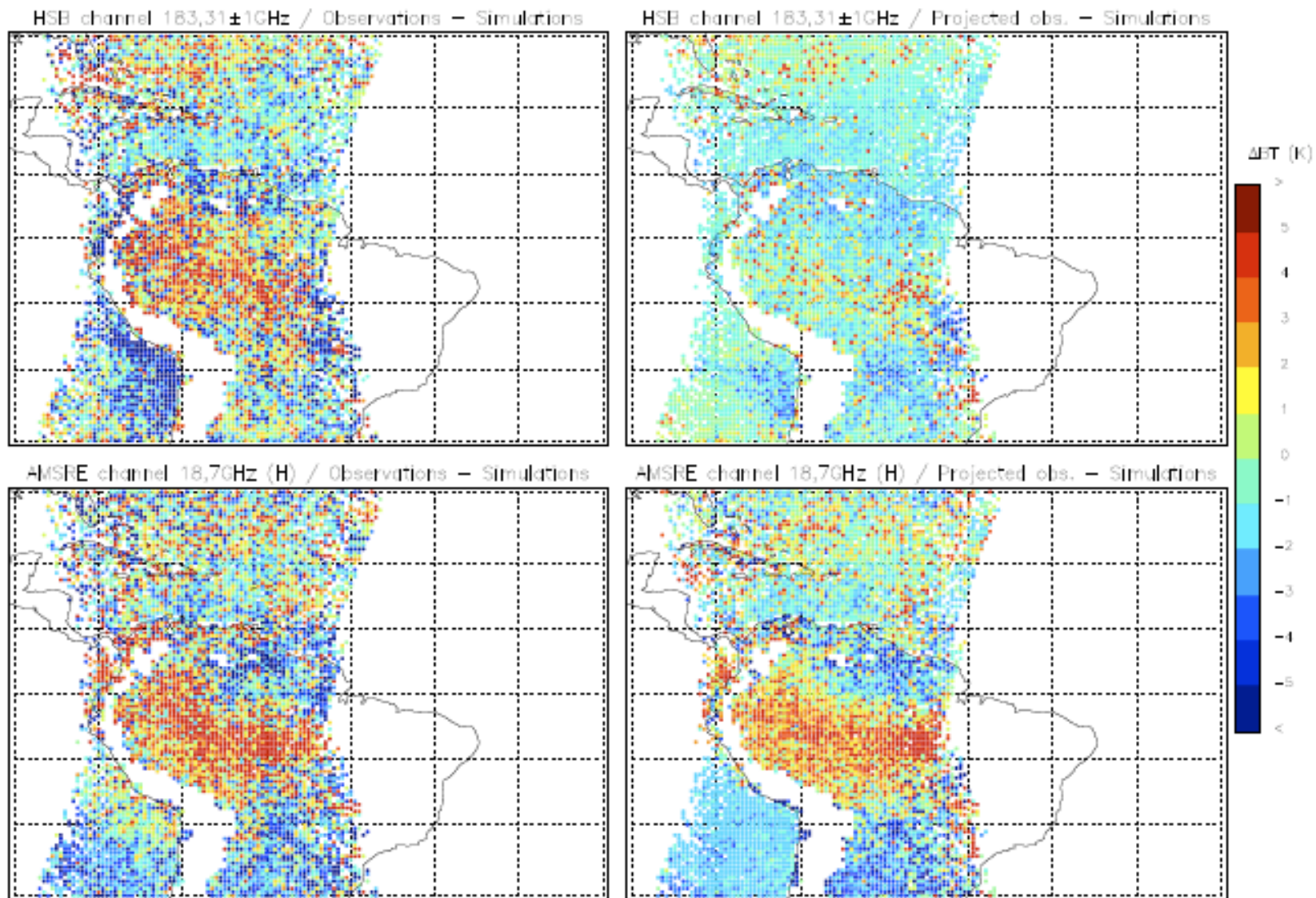


FIG. 3. Root Mean Square (RMS) error maps computed over two months for differences between RTTOV simulations and real AQUA observations (left) or calibrated AQUA observations (right): for a HSB channel at 183.31 ± 1 GHz (top) and a AMSR-E channel at 18.7 GHz vertically polarized (bottom).

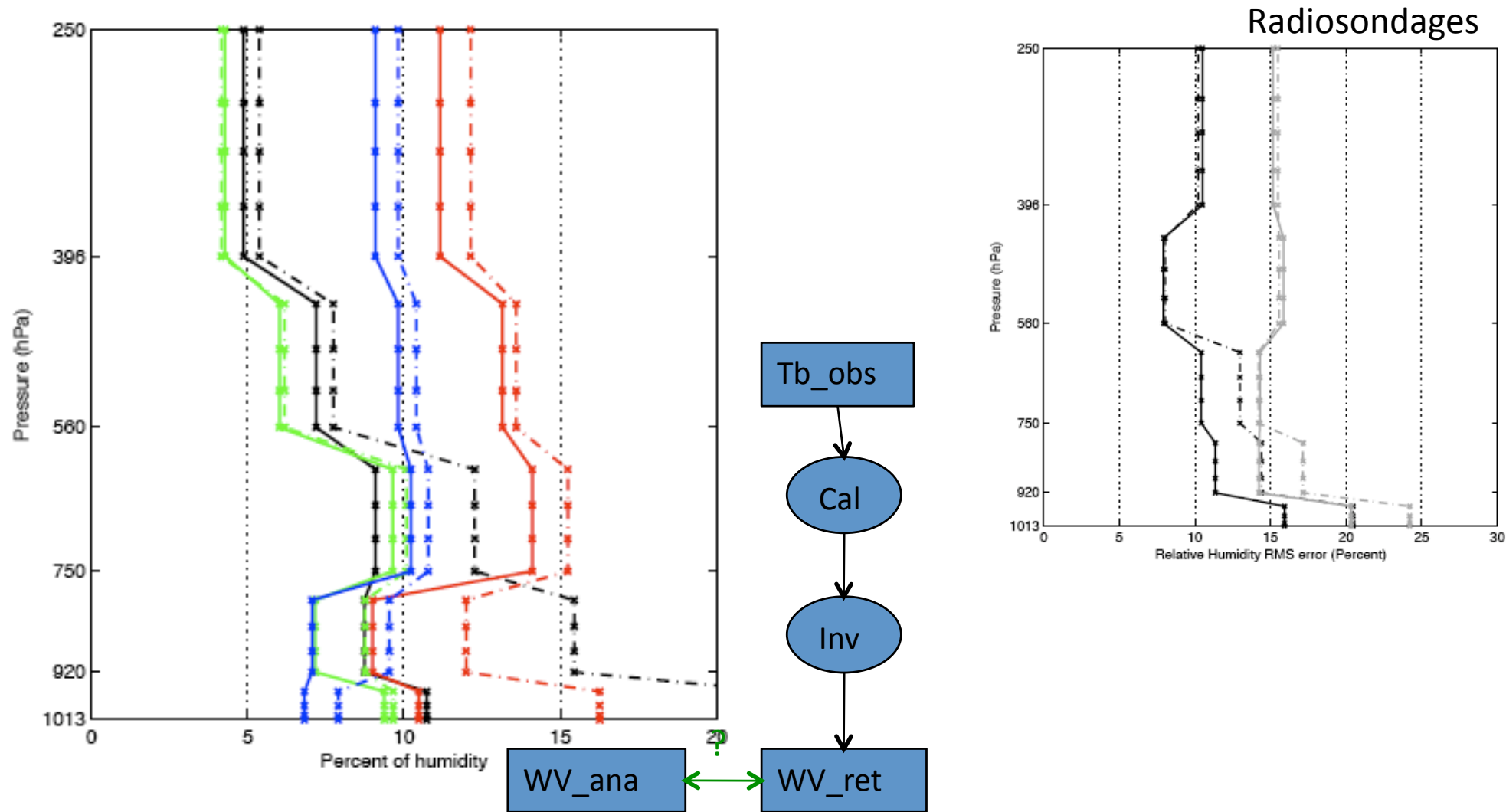
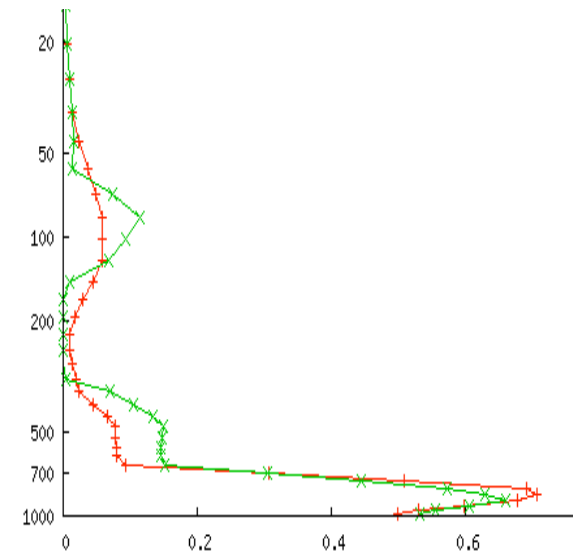
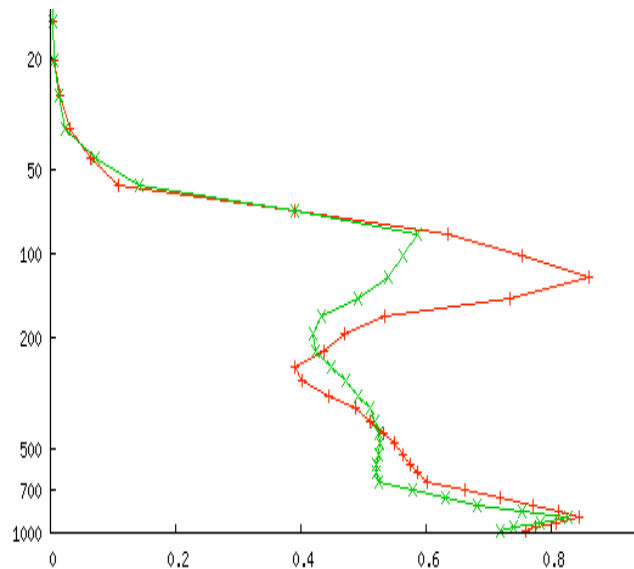
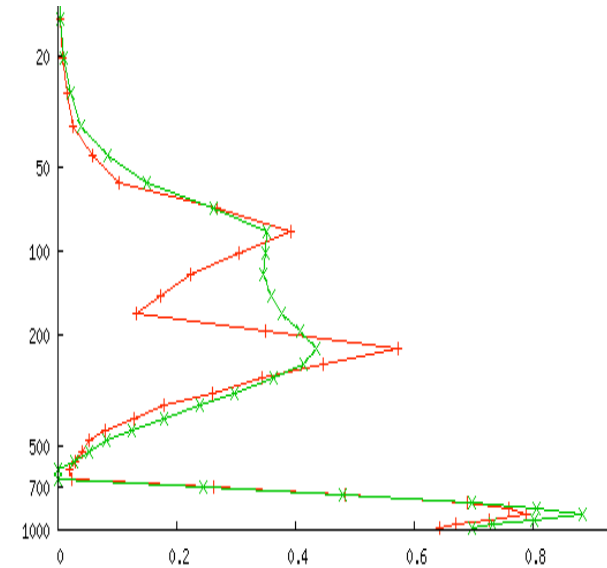
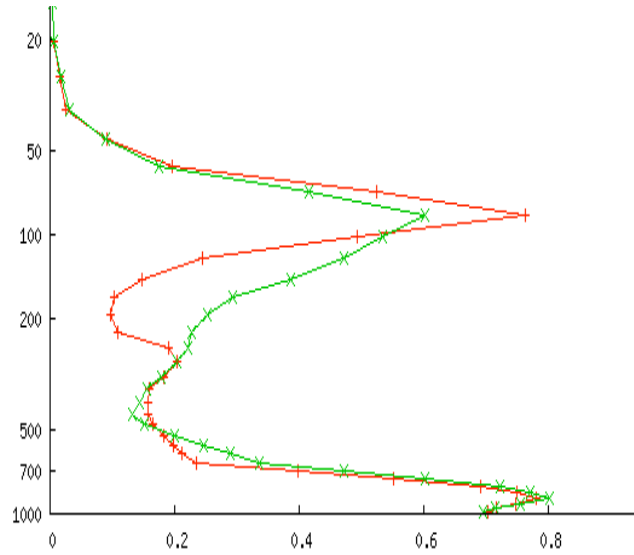


FIG. 5. Root Mean Square relative humidity departure of the ECMWF analysis and the retrieval from raw (dotted) and calibrated (continuous line) AQUA observations: for Cloud Free/Land (black), Cloudy/Land (green), Cloud Free/Ocean (red) and Cloudy/Ocean (blue) configurations.

Retrieval examples



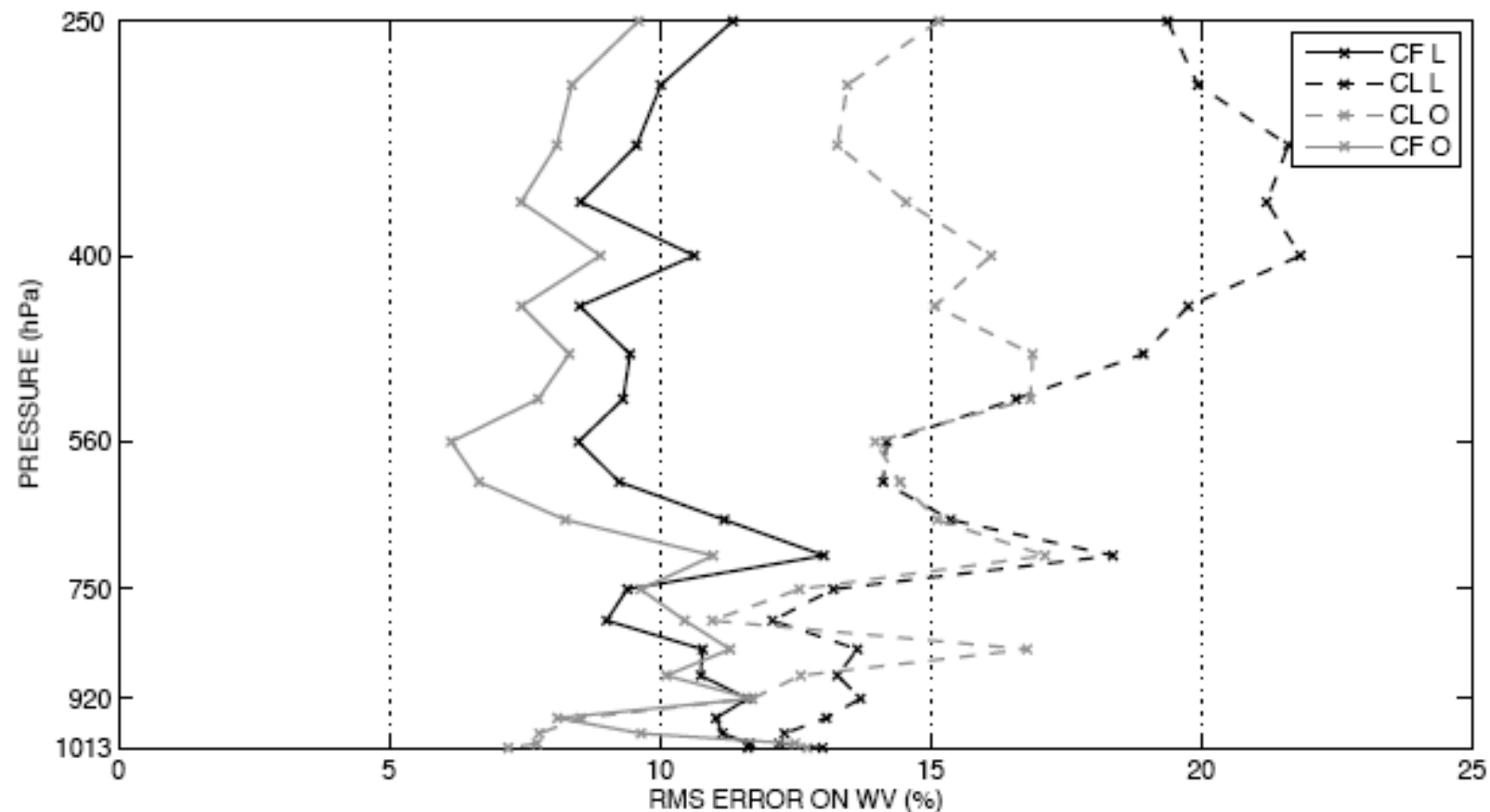
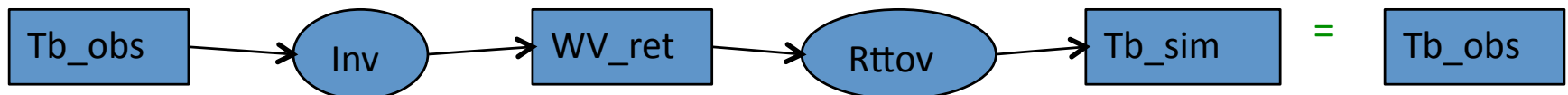
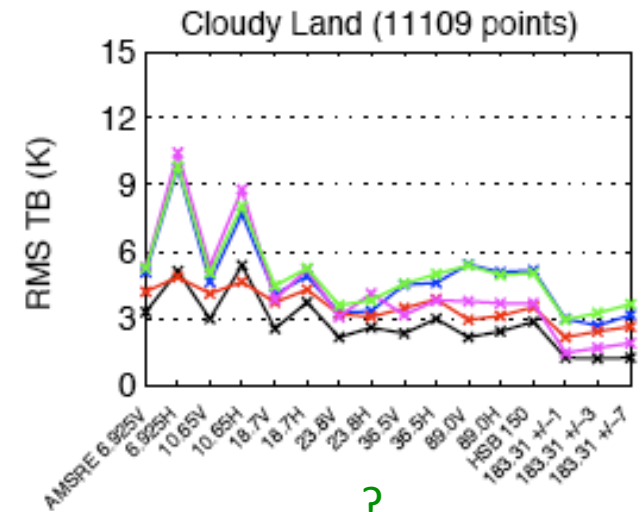
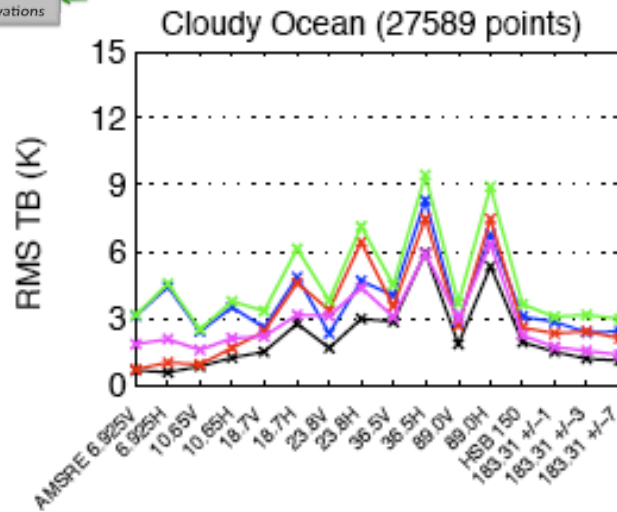
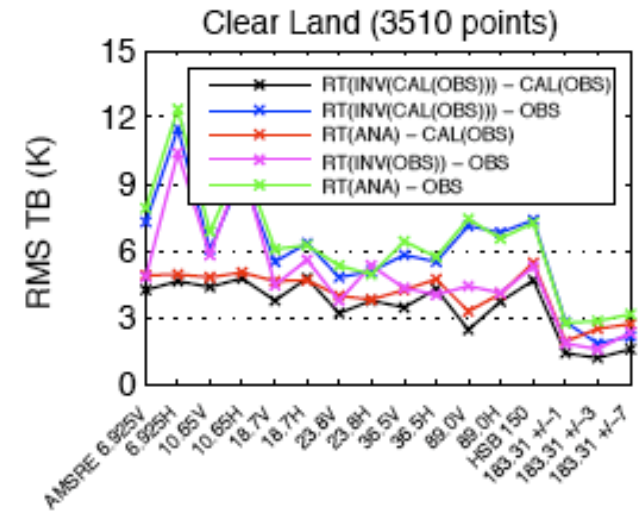
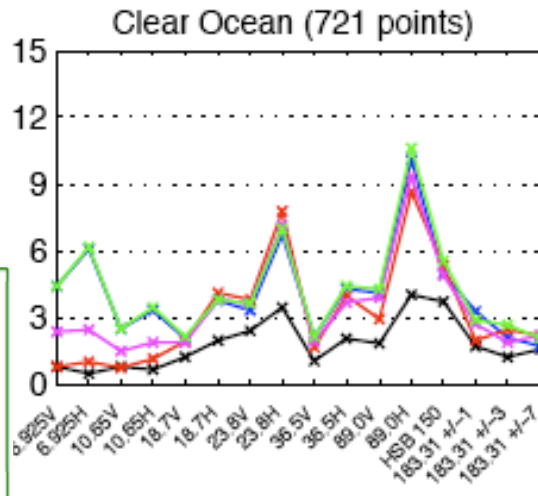
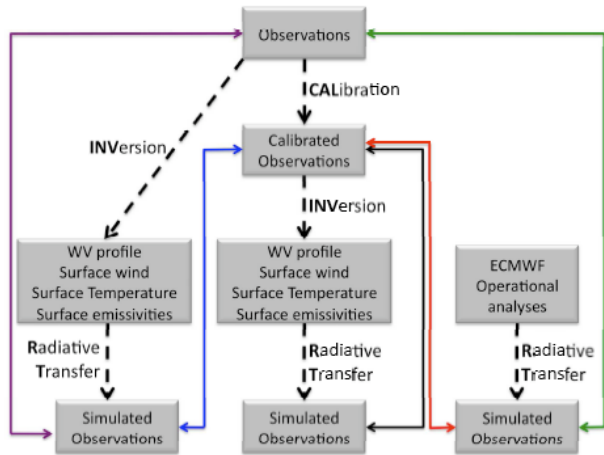


Figure 5. RMS relative error for the AMSR-E/HSB retrieval of relative humidity (in %). The statistics are given over the Tropical regions ($\pm 30^\circ$) for July 2002 and January 2003. Grey lines are for ocean surfaces (O) and black lines for land (L). Continuous lines are for Cloud Free (CF) scenes and dashed lines are for CLoudy (CL) situations.

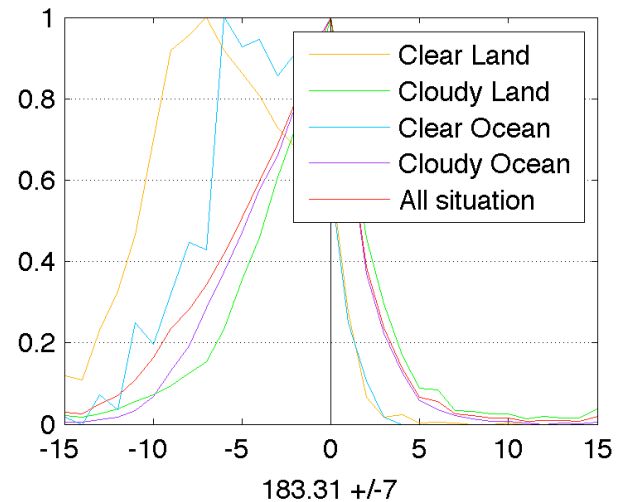
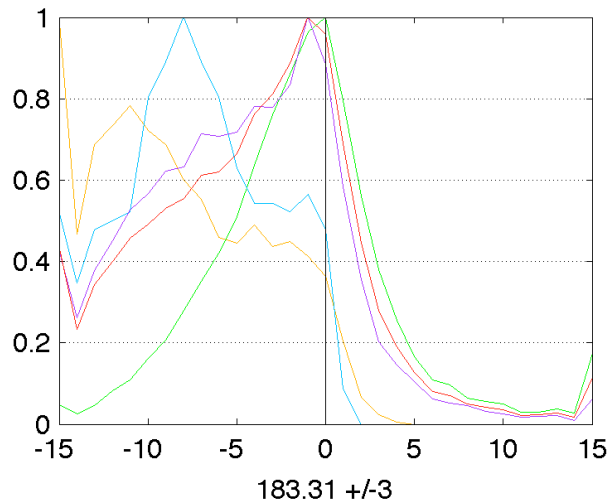
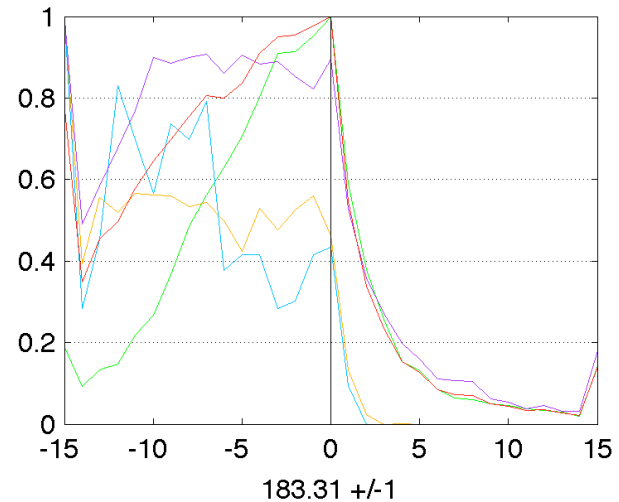
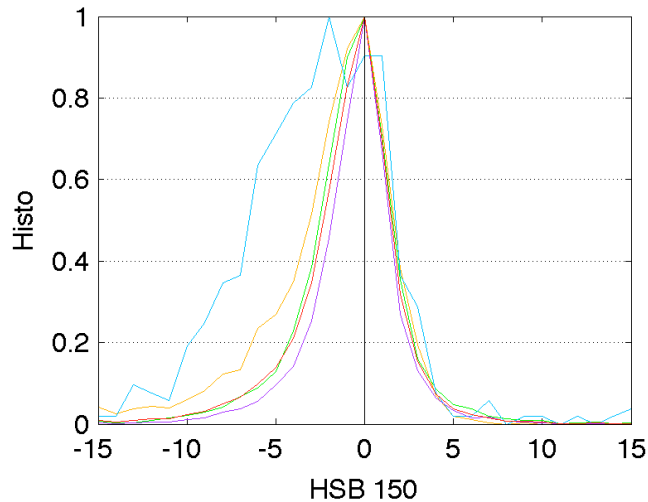
Validation on the TB-space



Validation on the TB space (4/5)

TB_error_ret - TB_error_ana

HSB

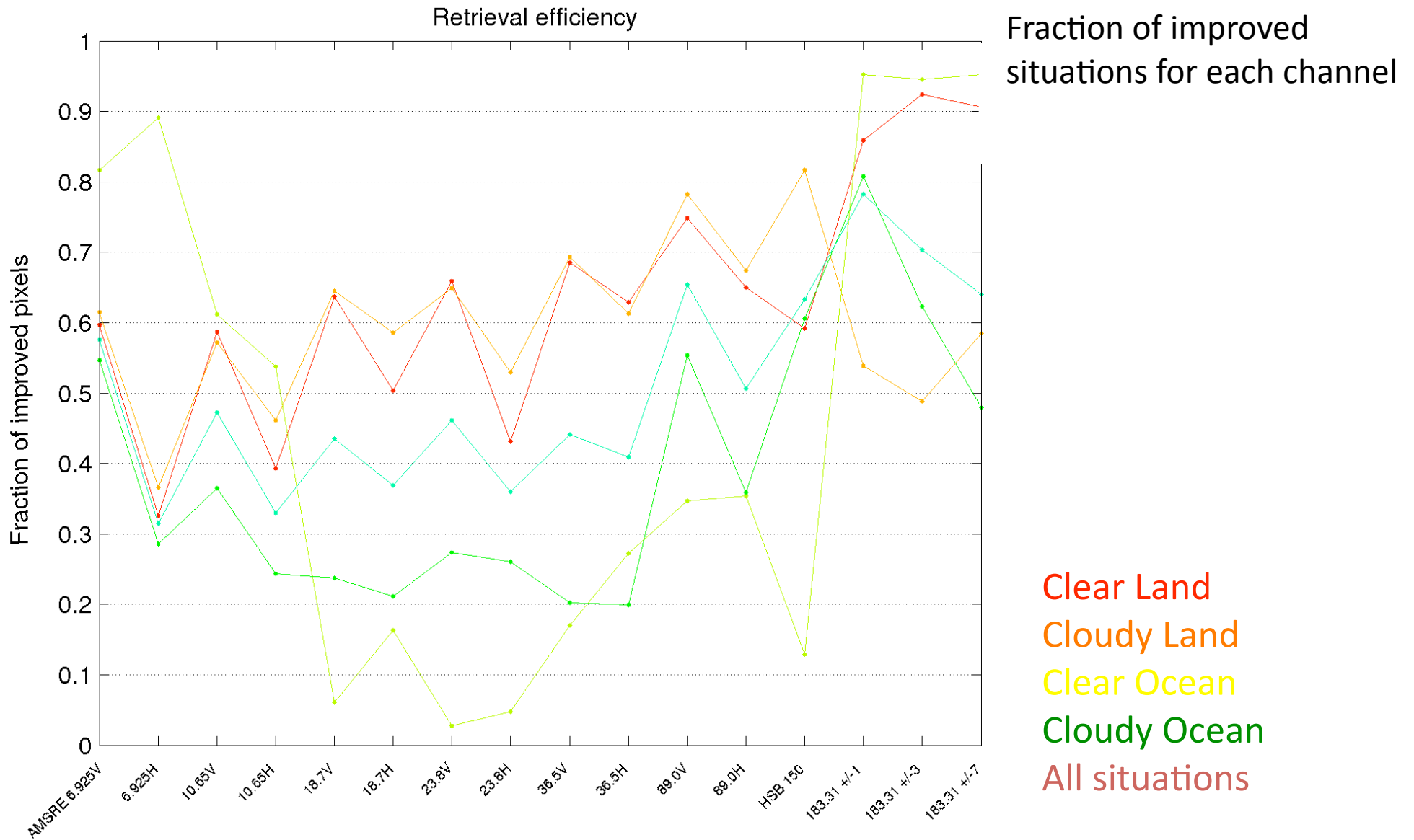


Clear Land
 Cloudy Land
 Clear Ocean
 Cloudy Ocean
 All situations

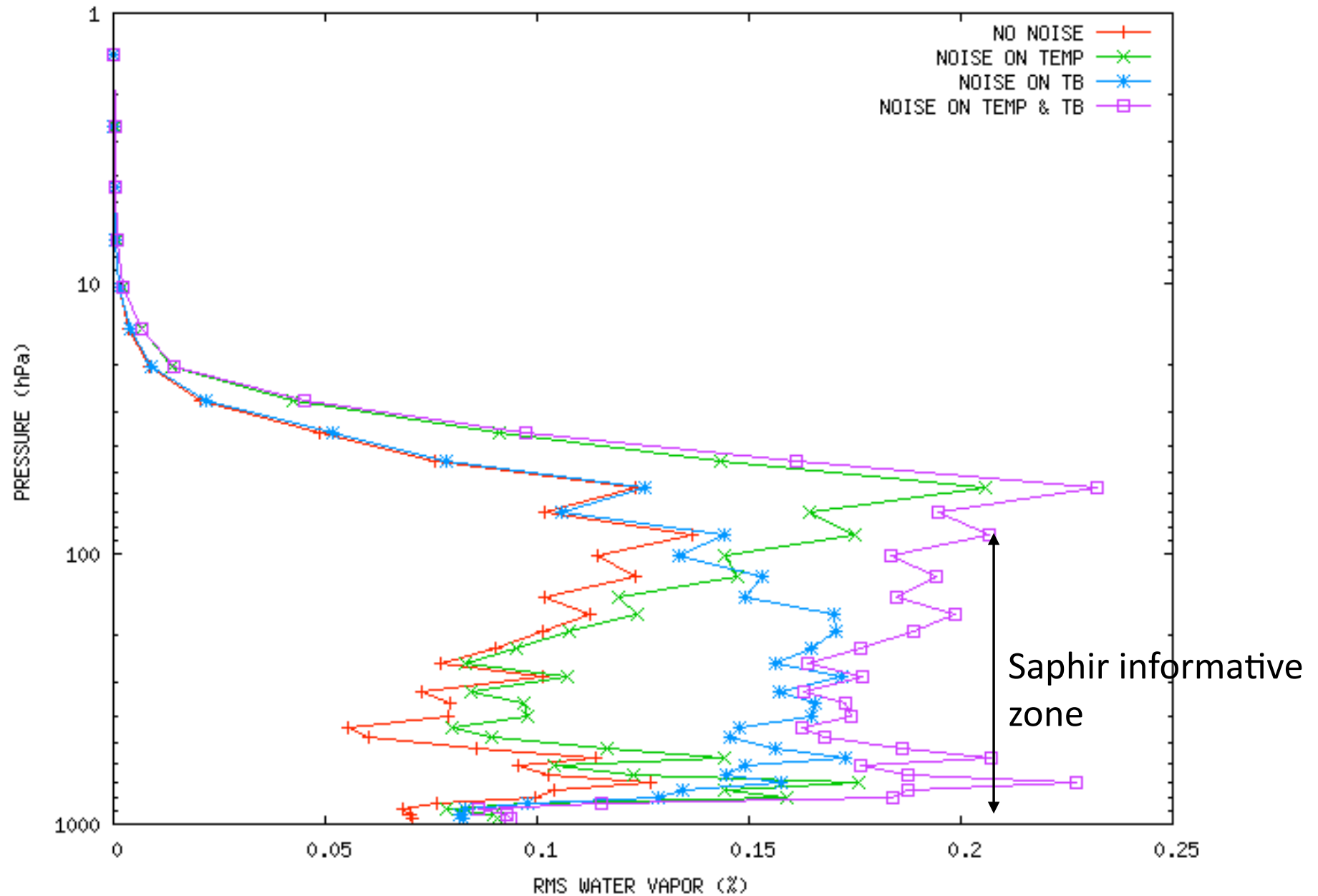
- Positive: degrade the analysis
- Negative: improve the analysis

Very important improvement
 on WV channels

Validation on the TB space (5/5)



Sensitivity to uncertainties



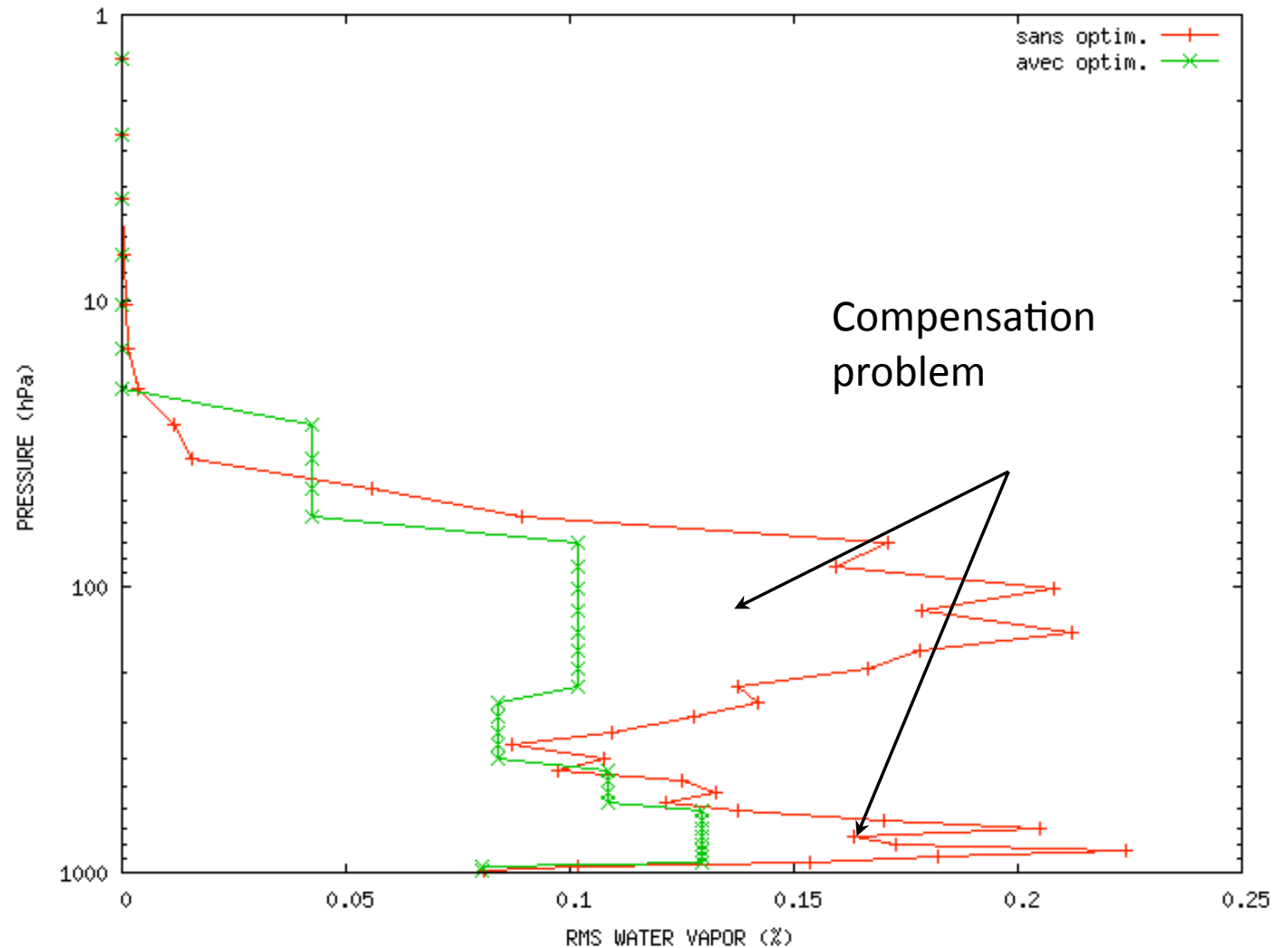
Optimization of retrieval layers

We don't perform retrieval in the high-layers and 6 undefined **layers** are considered in the low-atmosphere with variable size.

↓
Automatic optimization

↓
-10 layers

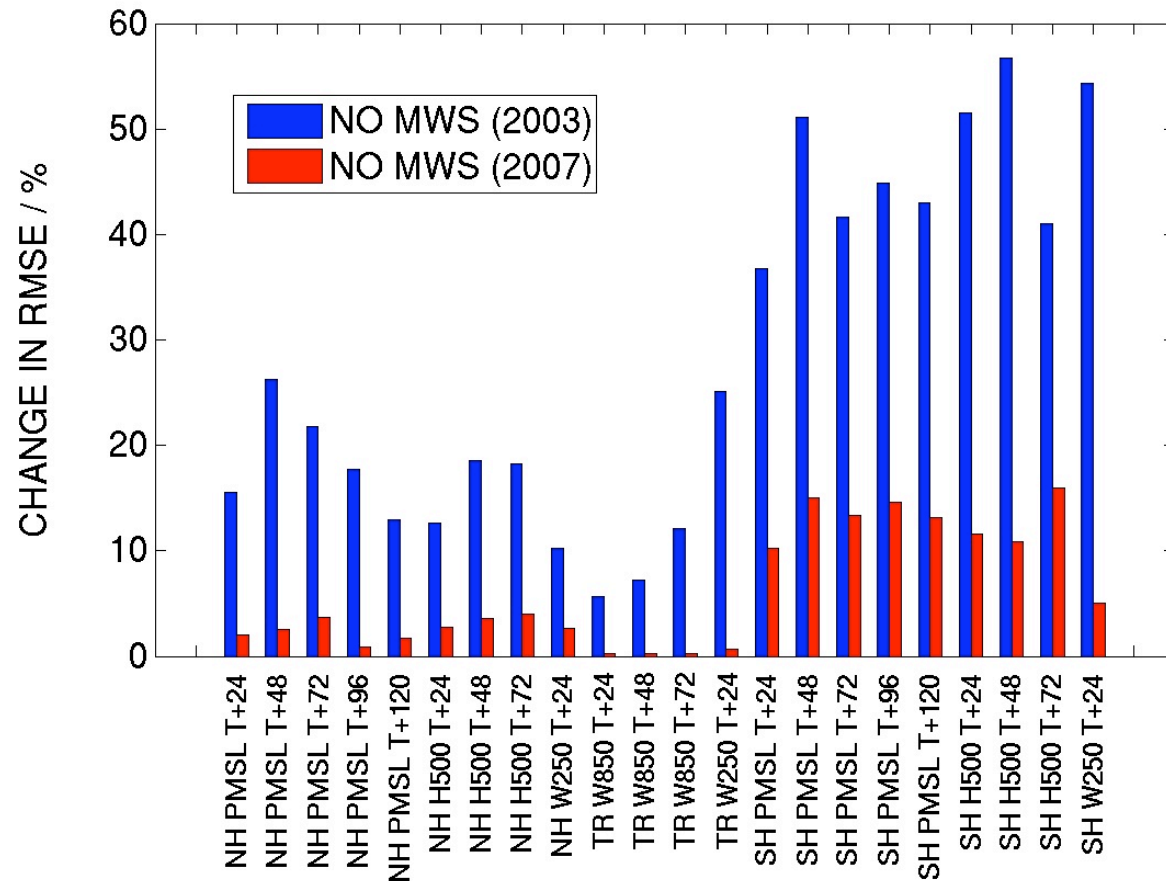
- 4 layers
- 8 layers
- 5 layers
- 4 layers
- 8 layers
- 4 layers



Conclusions/Perspectives

- Restitution de la WV
- Possible de faire des restitutions au dessus des continents grâce aux outils développés ces 15 dernières années
- Problèmes de calibration (pour l'inversion, inter-instruments et pour les drifts instrumentaux)
- Validations difficiles
- Perspectives:
 - Analyse de la variabilité de la WV avec de potentiels post-traitements (interpolations temporelles et spatiales)
 - Amélioration des chaînes existantes, développement d'une climatologie
 - Synergie avec l'infrarouge (présentation Maxime Paul)

Impact of microwave sounder data in NWP: Met Office OSEs



2003 OSEs:

- N-15, -16 and -17 AMSU
- N-16 & N-17 HIRS
- AMVs
- Scatterometer winds
- SSM/I ocean surface wind speed
- Conventional observations

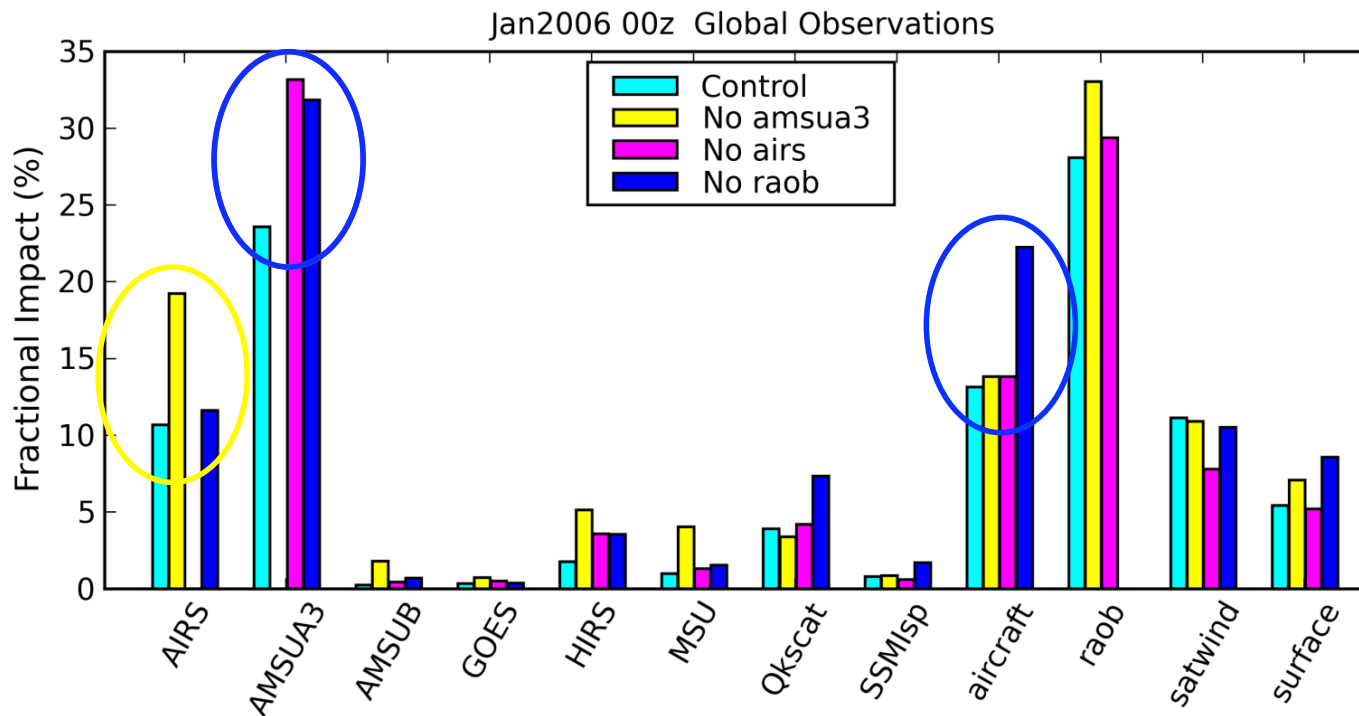
2007 OSEs:

- N-16, N-18, MetOp-2 AMSU
- SSMIS
- AIRS & IASI
- Scatterometer winds
- AMVs
- SSM/I ocean surface wind speed
- Conventional observations

(W. Bell)

Combined Use of ADJ and OSEs (Gelaro *et al.*, 2008)

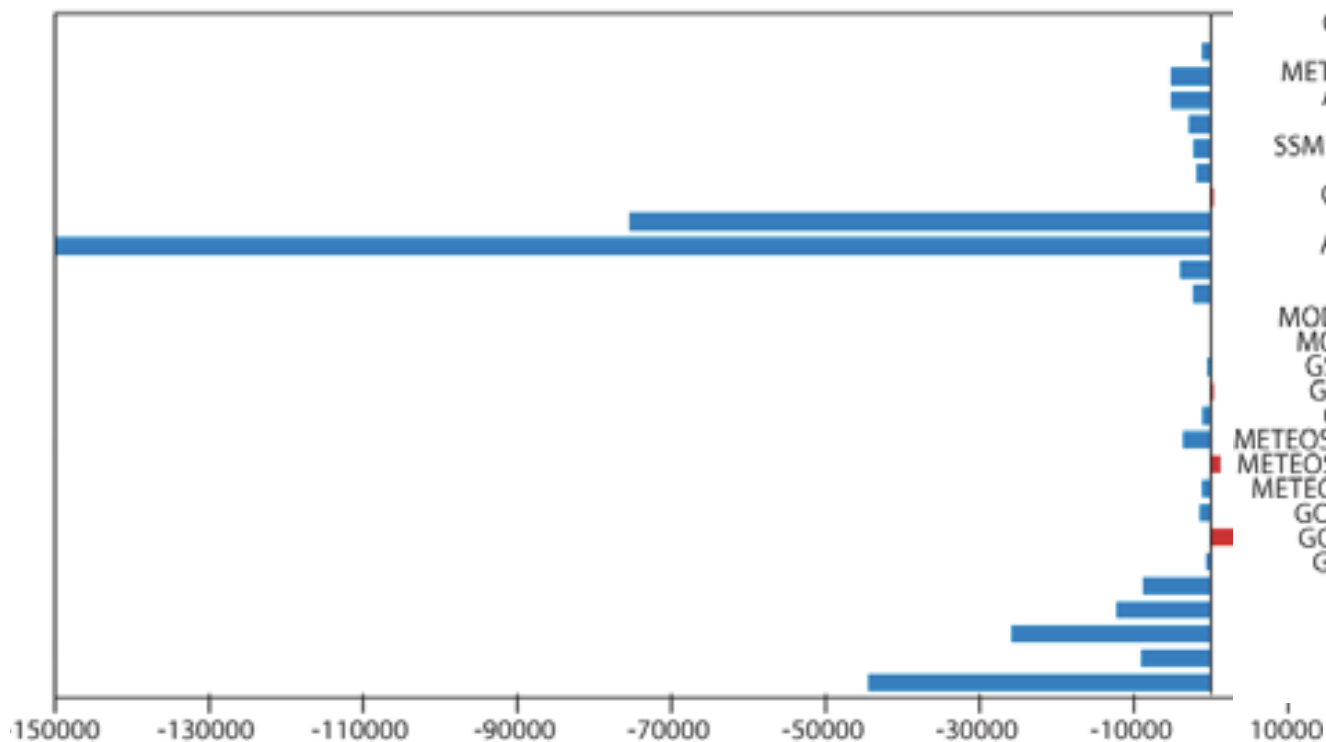
...ADJ applied to *various* OSE members to examine how the mix of observations influences their impacts



- Removal of AMSUA results in large increase in AIRS (and other) impacts
- Removal of AIRS results in significant increase in AMSUA impact
- Removal of raobs results in significant increase in AMSUA, aircraft and other impacts (but not AIRS)

Forecast sensitivity to observation (FSO) as a diagnostic tool

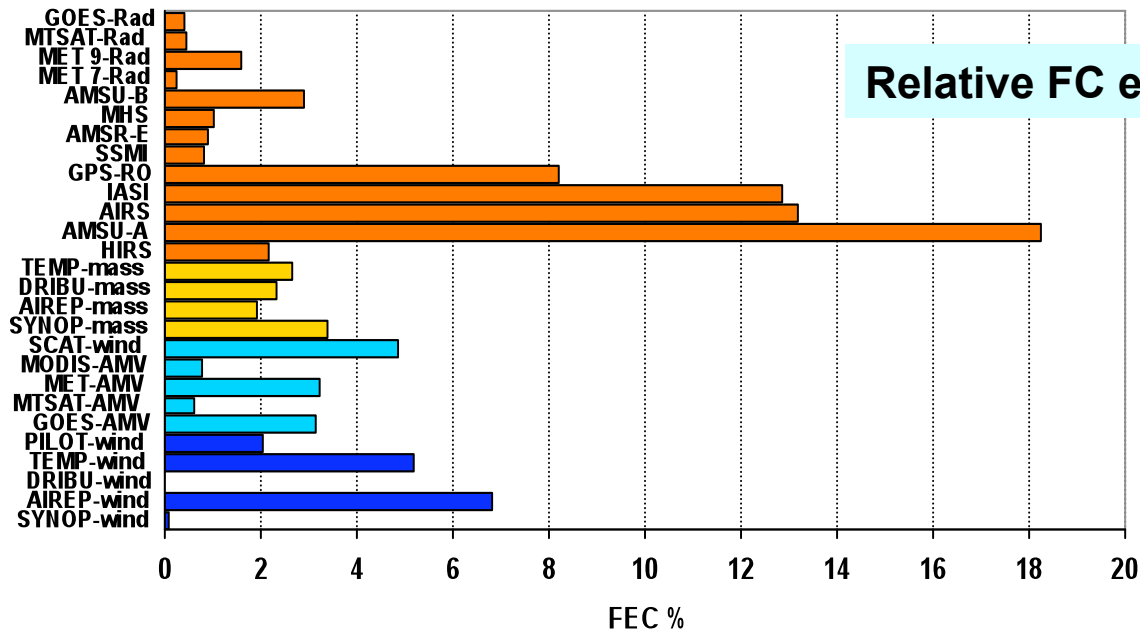
Carla Cardinali, October 2009



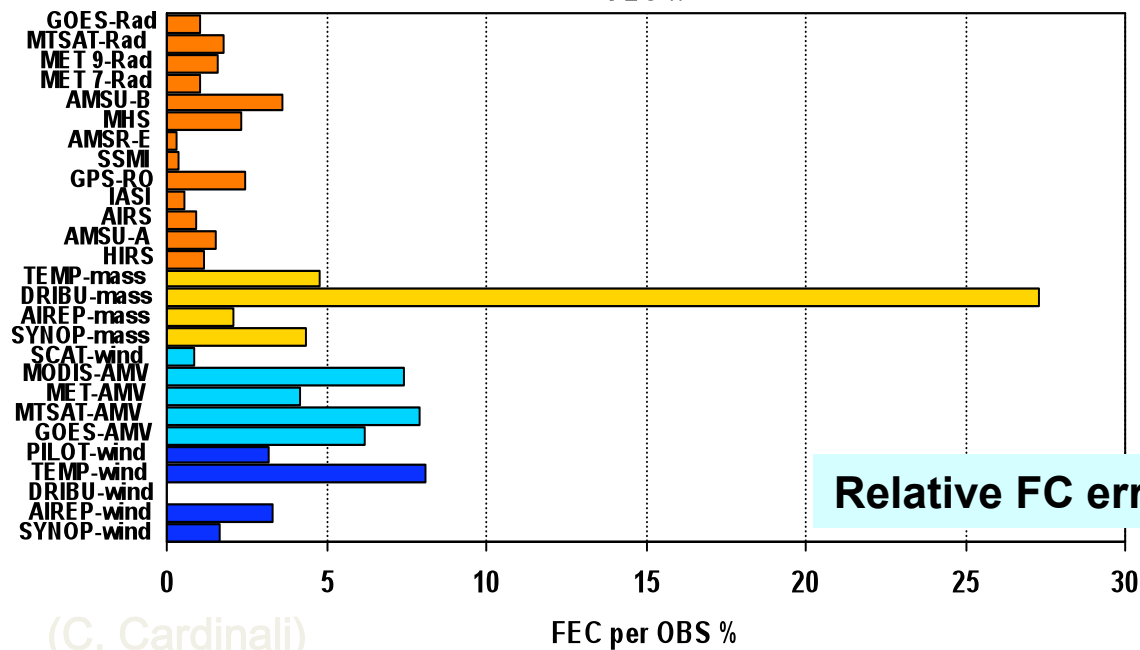
24-hour forecast error contribution in J/kg of the components (types) of the observing system in winter 2007. Negative (positive) values correspond to a decrease (increase) in the energy norm of forecast error. FSO uses a third order sensitivity gradient.

The impact of all types of observations on the short-range forecast has increased impressively. It has been shown that microwave satellite measurements (AMSU-A) are responsible for 18% of the forecast error reduction, infrared measurements (AIRS and IASI) for 12% and 10% of error reduction is due to radio occultation observations. Conventional observations (surface pressure, vertical profiler and aircraft) are as well decreasing the forecast error, being responsible for an average reduction of 6%.

Advanced diagnostics



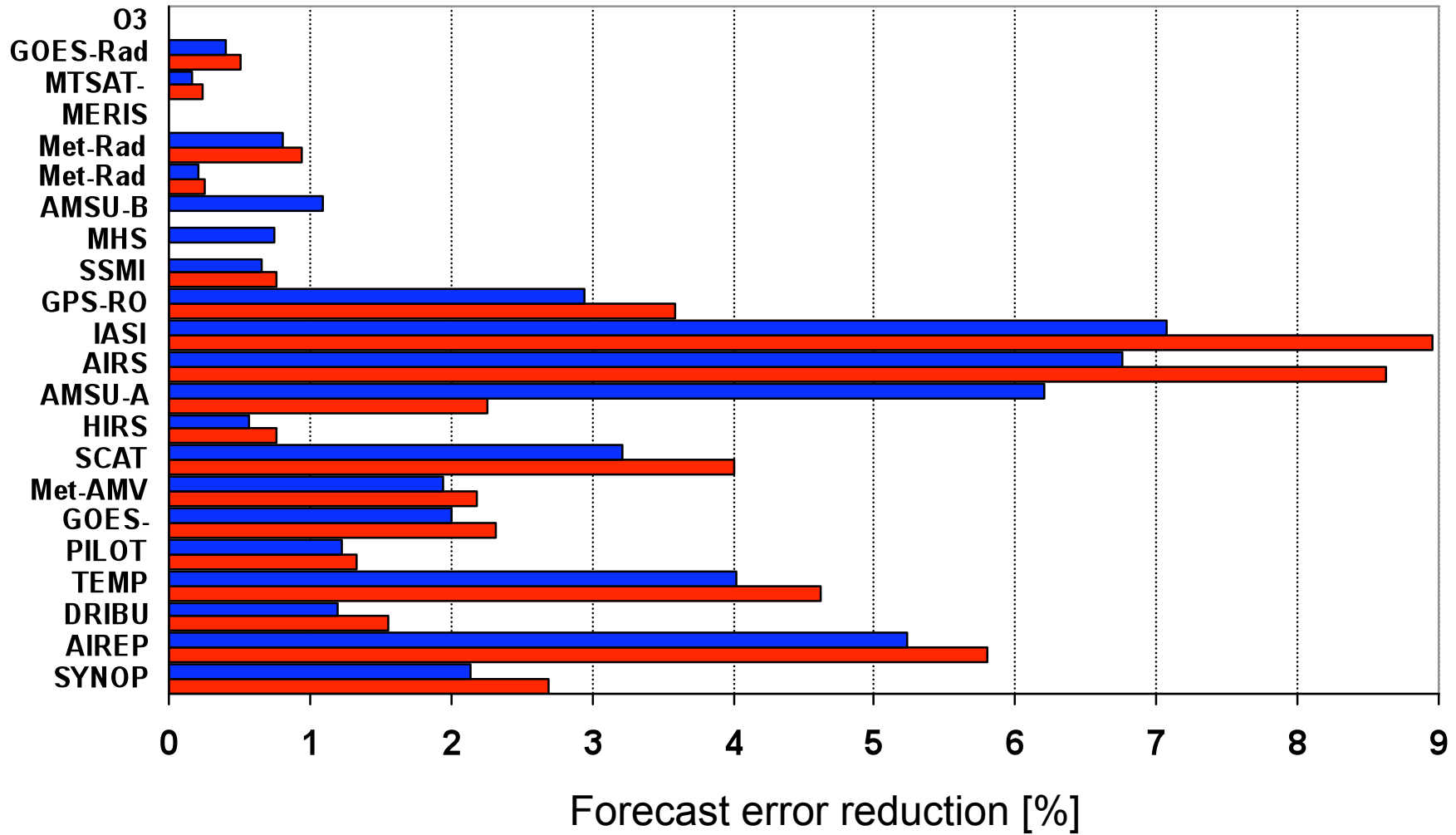
The *forecast sensitivity* (Cardinali, 2009, QJRMS, 135, 239-250) denotes the sensitivity of a forecast error metric (dry energy norm at 24 or 48-hour range) to the observations. The forecast sensitivity is determined by the sensitivity of the forecast error to the initial state, the innovation vector, and the Kalman gain.



(C. Cardinali)

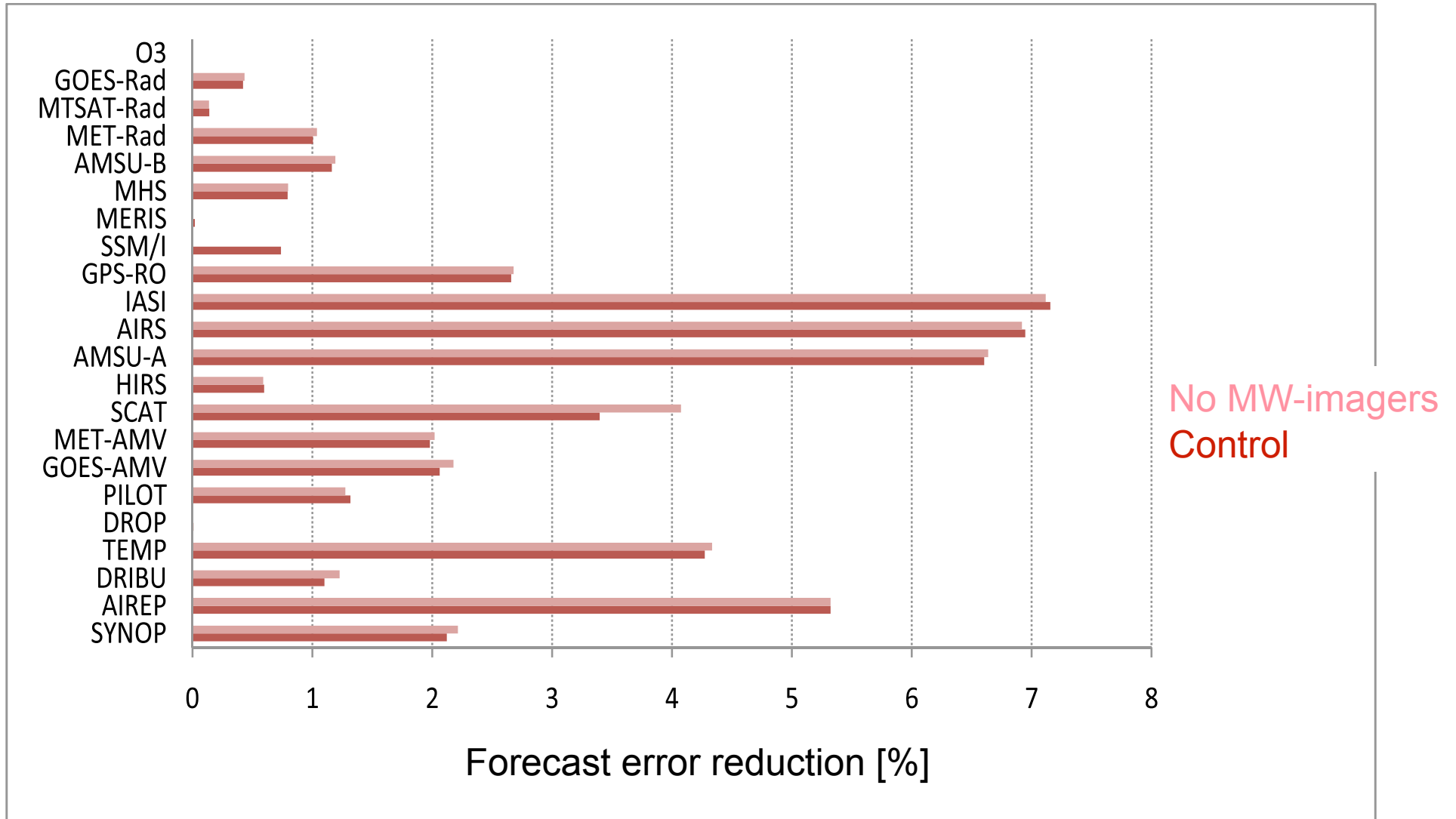
Advanced diagnostics – MW sounder denial

3 AMSU-A, 2 MHS vs **1 AMSU-A, 0 MHS**



(C. Cardinali)

Advanced diagnostics – MW imager denial



(C. Cardinali)